

Lecture: Algorithmic Bioinformatics

Doctoral School, Université Dauphine, 2022



**Université
Gustave Eiffel**

Lecture Overview

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- Introduction
 - ▶ Molecular Biology
 - ▶ Sequencing
 - ▶ Assembly
 - ▶ Scaffolding
- Phylogenetics
- ...

Laurent Bulteau

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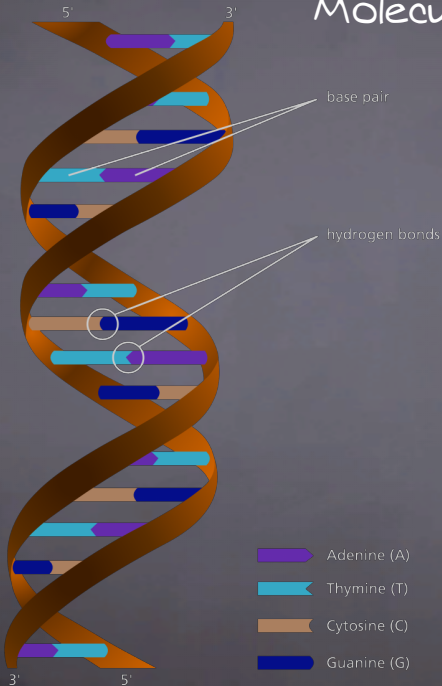


- Genome Rearrangements
- ...
- Scaffold Filling

Molecular Biology Basics

DNA

- double strand
- nucleotides paired: A-T, C-G
- inside nucleus (eucaryotes)



Molecular Biology Basics



DNA

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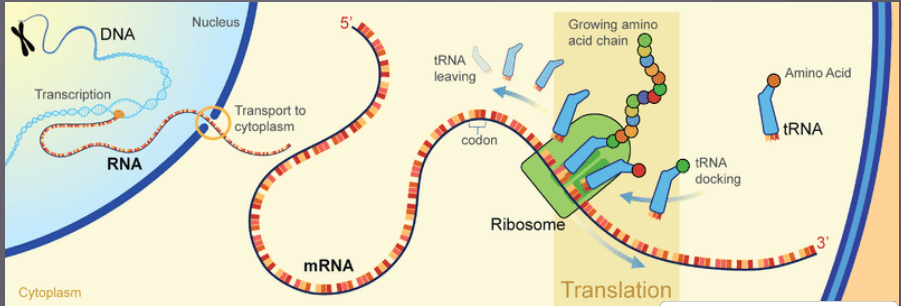
RNA

- single strand
- transported outside nucleus
- translated into actual proteins
- Thymine (T) → Uracil (U)

Molecular Biology Basics

Transcription ≠ Translation

DNA → RNA ≠ RNA → protein



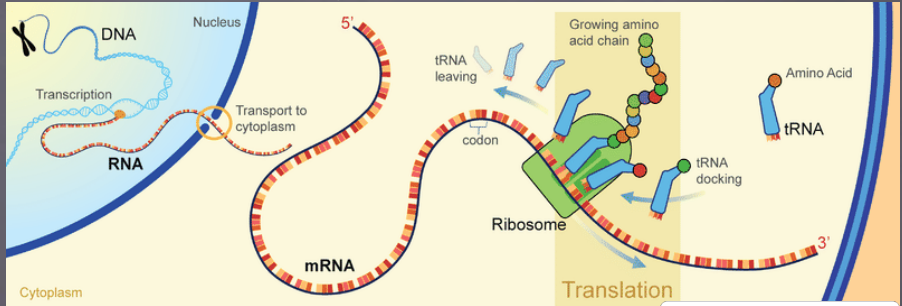
ck-12

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Molecular Biology Basics

Transcription ≠ Translation

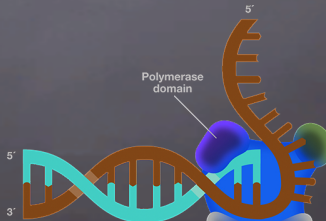
DNA → RNA ≠ RNA → protein



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Polymerase

single strand → double strand

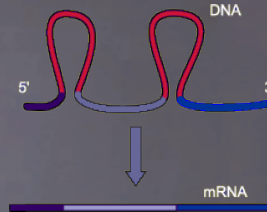


Molecular Biology Basics

Introns & Exons

parts of DNA cut out when forming mRNA ("splicing")

- removed \rightsquigarrow "intron"
- not removed \rightsquigarrow "exon"

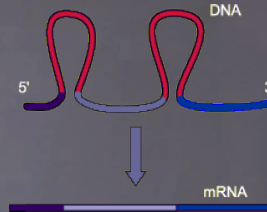


Molecular Biology Basics

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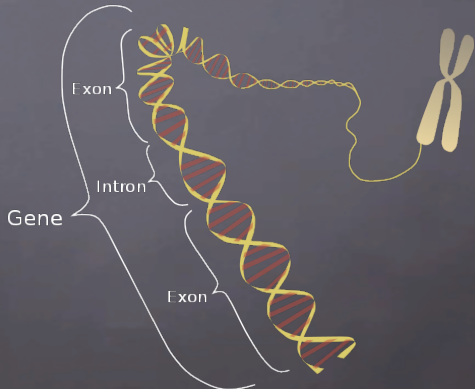
parts of DNA cut out when forming mRNA ("splicing")

- removed \rightsquigarrow "intron"
- not removed \rightsquigarrow "exon"



Gene

Gene = START...STOP
(including introns)
(10^3 - 10^5 Bp)



Molecular Biology Basics



Chromosomes

- haploid = 1 set of chromosomes
- diploid = 2 sets of chromosomes (usually one from each parent)
- ... ("polyploid")
- procaryotes \rightsquigarrow one (circular) chromosome, haploid
- eucaryotes \rightsquigarrow set of (linear) chromosomes, polyploid



44



90



16



46



46

Mutation

Single-Nucleotide Polymorphism

- DNA damage
- caused by radioactivity, UV light, ...

Mutation

..AATC**G**CTAA..
..AATCCTAA..

Single-Nucleotide Polymorphism

- DNA damage
- caused by radioactivity, UV light, ...
- insertion,

Mutation

..AATCCTAA..
..AATC**G**CTAA..

Single-Nucleotide Polymorphism

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- caused by radioactivity, UV light, ...
- insertion, deletion,

Mutation

..AATC**G**CTAA..
..AATC**A**CTAA..

Single-Nucleotide Polymorphism

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Replication Error

- DNA rearrangement
- caused by errors in Meiosis/Mitosis

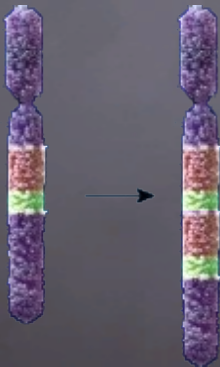
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- duplication,



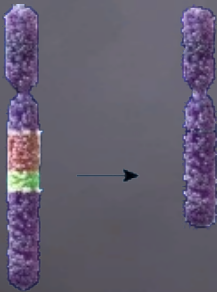
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Single-Nucleotide Polymorphism

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Replication Error

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- duplication, deletion (loss),



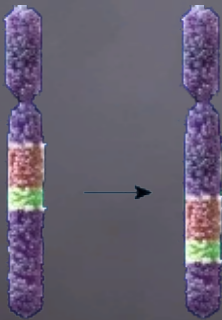
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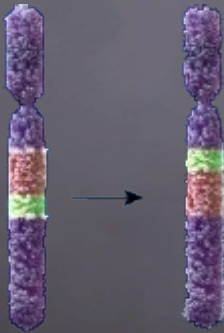
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Replication Error

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Mutation



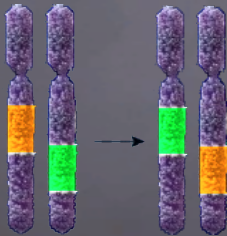
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- duplication, deletion (loss), translocation, inversion,

Mutation



Single-Nucleotide Polymorphism

- DNA damage
- caused by radioactivity, UV light, ...
- insertion, deletion, substitution

Replication Error

- DNA rearrangement
- caused by errors in Meiosis/Mitosis
- duplication, deletion (loss), translocation, inversion, crossover

Sanger Sequencing

[Sanger et al '77]

CCTGGACGGGTCAGACATGACAGTGGCCCCAAGATTACAAAGATCGTATCTCAATACAGTAAACGAGCAAT
GGACCTGCCCAGTCTGTACTGTCACCGGGGTTCTAAGTGTTCCTAGCATAGAGTTATGTCATTTGCTCGTTA

Sanger Sequencing

1. make thousands of copies of target ("amplified genome")

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[Sanger et al '77]

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2. split their helix

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4. add a special Base: A* (polymerase cannot extend)

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6. measure the length of each fragment
 ~> each length is the position of a T in the template

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 ~> each length is the position of a T in the template

Problems

- frequency of longer reads decreases drastically
- length-estimate unreliable after a couple hundred bp
 ~> chop DNA into pieces and read those
- repeated Bases unreliable

Next Generation Sequencing (illumina)



Next Generation Sequencing (illumina)

ACTCA.....ACCTC

Preparation

1. chop DNA into smaller pieces (approximate size known)

Next Generation Sequencing (illumina)

TGGTACTCA ACCTCTCAG

Preparation

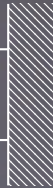
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2. add anchors (and IDs) to each end of each piece

Next Generation Sequencing (illumina)

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AGTC

ACCA



Preparation

1. chop DNA into smaller pieces (approximate size known)
2. add anchors (and IDs) to each end of each piece
3. "flow cell" containing anchor places

Next Generation Sequencing (illumina)

TGGTACTCA ACCTC

AGTC
TCAG

ACCA



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1. chop DNA into smaller pieces (approximate size known)
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Amplification

1. strand anchors its two ends to two anchor places

Next Generation Sequencing (illumina)



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CTGAGAGGT.....TGAGTACCA



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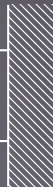
Sequencing

1. add special (fluorescent, non-extendable) bases + polymerase

Next Generation Sequencing (illumina)

TGGTACTCA ACCTCTCAG

CTGAGAGGT TGAGTACCA



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Sequencing

1. add special (fluorescent, non-extendable) Bases + polymerase
2. polymerase attaches one Base

Next Generation Sequencing (illumina)

TTGTA^{red}ACTCA.....ACCTC^{blue}TCAG

CTGA^{blue}GAGGT.....TGAGT^{red}ACCA



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3. camera takes picture of the flow cell

Next Generation Sequencing (illumina)

TGGTACTCA ACCTCTCAG

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2. polymerase attaches one Base
3. camera takes picture of the flow cell
4. rinse, repeat (last 3 steps) until no more Bases were added

Next Generation Sequencing (illumina)

TGGTACTCA.....ACCTCTCAG

CTGAGAGGT.....TGAGTAC

"Paired-End reads"

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Amplification

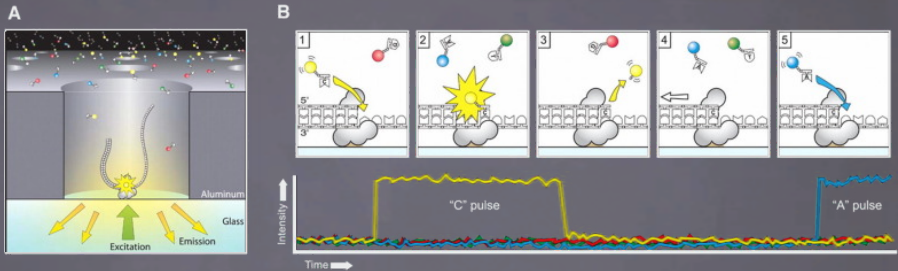
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2. polymerase attaches one Base
3. camera takes picture of the flow cell
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distance between reads
=
"insert size"

Third-Gen Sequencing: SMRT



[Rhoads et al, 2015]

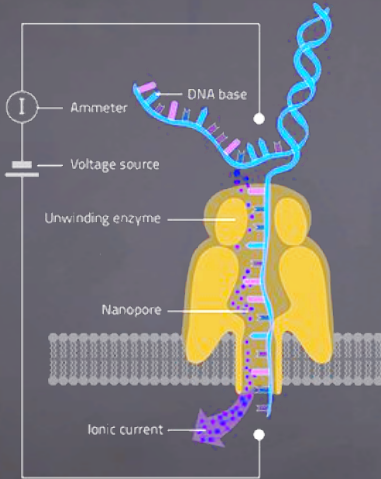
Single Molecule Real Time Sequencing

1. fix a polymerase enzyme under a microscope
2. attach fluorescent molecule to each nucleotide
3. polymerase clips off fluorescent molecule when attaching a base
4. observe change in fluorescence \leadsto identify base

Third-Gen Sequencing: PacBio

Nanopores

1. "pore" of diameter 1-20nm
2. only single-strand may pass
3. Base at "bottleneck" hinders current
4. \leadsto "characteristic profile" determines Base



Conclusion: Sequencing

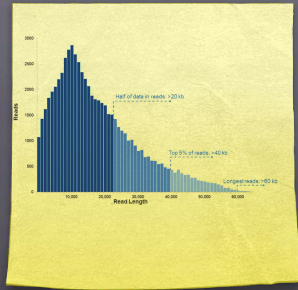
method	read length	% errors	reads/s	\$/MBase
Sanger	600-1000	0.001	0.03	500
Illumina HiSeq	2×250	0.1	4000	0.04
SMRT (PacBio)	10^4	13	3.4	0.50
NanoPore (minION)	$5 \cdot 10^3$	38	0.3	11

[Rhoads et al, 2015]

Conclusion: Sequencing

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Sequence Assembly: Overview

GCCCCTGAACTTCGCTAGGGTTCTCTAACGACACTCCTTGGGTTTTTACGTCGCGGTTCTCTAGGCCATTGATTGCGGGTCCAGGTGCTGTCAACGAC

Goal: reconstruct sequence

Problem 1: only have (small) reads

Idea: overlap reads to form complete sequence

Sequence Assembly: Overview

GGCCCTGAACCTTCGCTAGGGTTCTCTAACGACACTCCTTGGGTTTTTACGTCGCGGTTCTCTAGGCCATTGATTGCGGGTCCAGGTGCTGTCAACGA
GGCCCTGAACCTT CGACACTCCTTGGGTTTT CTAGGCCATTGATTGCGGGTC GGTCCAGGTGCTGTCAACGA
ACTTCGC GGTCTCT

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Sequence Assembly: Overview

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GGCCCTGAACCTT CGACACTCCTTGGGTTTT CTAGGCCATTGATTGCGGGTC
ACTTCGC GGTTCCT GGTCCAGGTGCTGTCAACGA
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GGCCCTGAACTT ACTTCGC CGACACTCCTTGGGTTTT CTAGGCCATTGATTGCGGGTC GGTCCAGGTGCTGTCAACGA
GGCCCTGAACTTCGC ACTTCGC CGACACTCCTTGGGTTTT GGTTCCTCT GGTCCAGGTGCTGTCAACGA
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~> sequence with "high coverage"

Sequence Assembly: Overview

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GCCCCTGAACTT CGACACTCCTTGGGTTTT CTAGGCCATTGATTGCGGGTC
ACTTCGC GGTTCCT GGTCCAGGTGCTGTCAACGA
TCGCTAGGGTTCTCTAACGA TTACGTCGCGG CGAC
GCCCCTGAACTTCGCTAGGGTTCTCTAACGACACTCCTTGGGTTTTTACGTCGCGGTTCTCTAGGCCATTGATTGCGGGTCCAGGTGCTGTCAACGA

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Overlap-Layout-Consensus Assembly

1. produce pairwise overlaps (All-Pairs Suffix-Prefix)

Overlap-Layout-Consensus Assembly

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Naive Overlap

AGGAGTC

GAGTCCA→

Overlap-Layout-Consensus Assembly

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Overlap-Layout-Consensus Assembly

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Naive Overlap

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$\leadsto O(\#reads^2 \cdot \text{read-length})$ time worst-case

Overlap-Layout-Consensus Assembly

1. produce pairwise overlaps (All-Pairs Suffix-Prefix)

Suffix Trees

annotate branches with strings such that:

1. each root→leaf path is a suffix (leaf labeled with start index)
2. no two siblings have a common prefix

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example: BANANA◇

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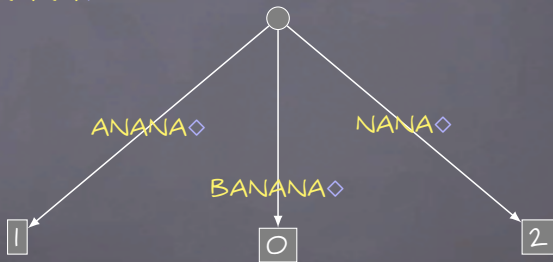
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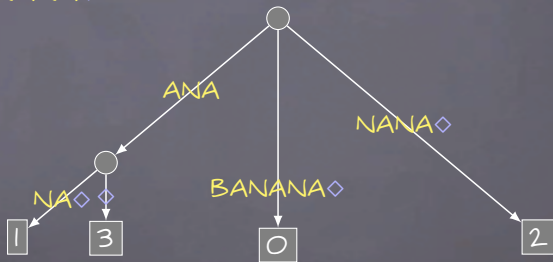
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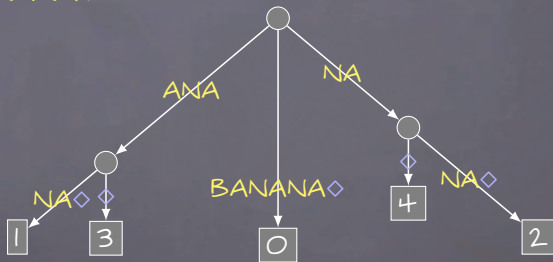
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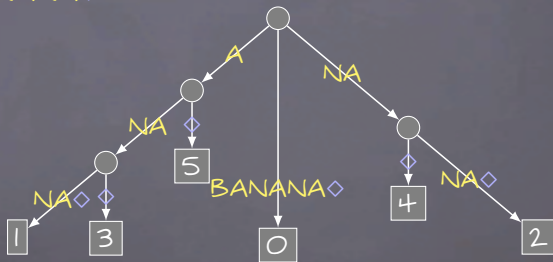
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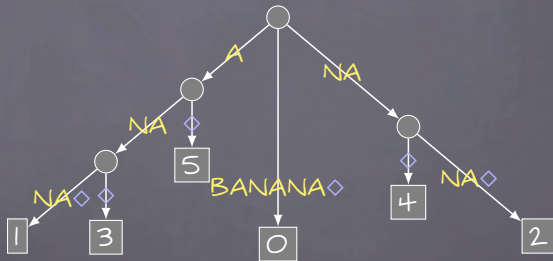
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Suffix Trees

annotate branches with strings such that:

1. each root \rightarrow leaf path is a suffix (leaf labeled with start index)
2. no two siblings have a common prefix

example: BANANA \diamond



$\leadsto O(\text{read-length}^2)$ time \nsubseteq space

Overlap-Layout-Consensus Assembly

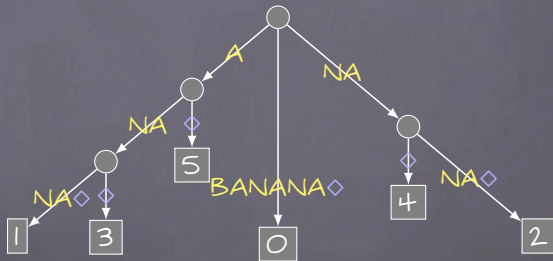
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$\leadsto O(\text{read-length}^2)$ time \nsubseteq space
can be improved to linear time \nsubseteq space

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exercise: joined suffix tree for AGGAGTC◊ and GAGTCCA▷



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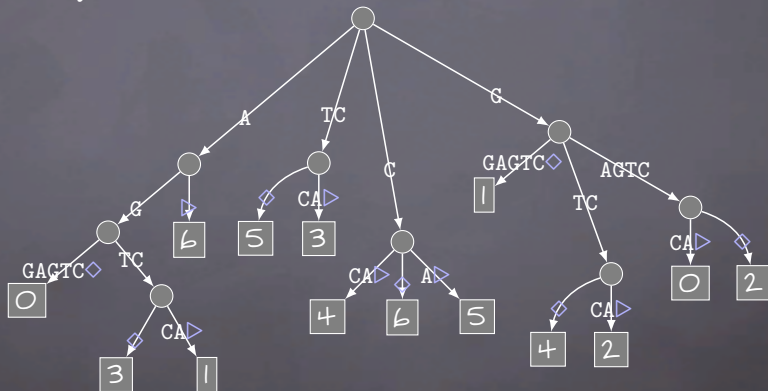
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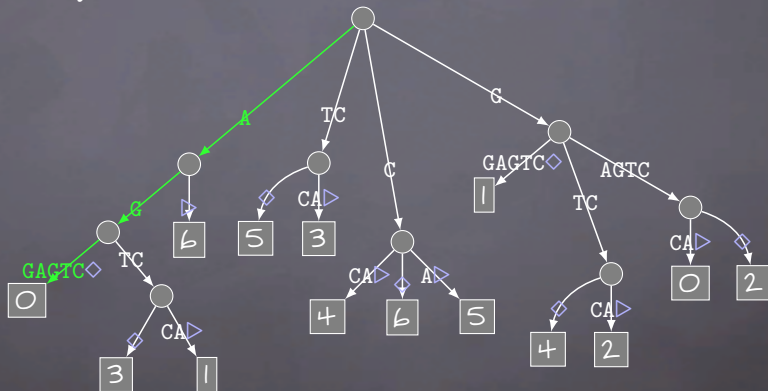
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Overlap-Layout-Consensus Assembly

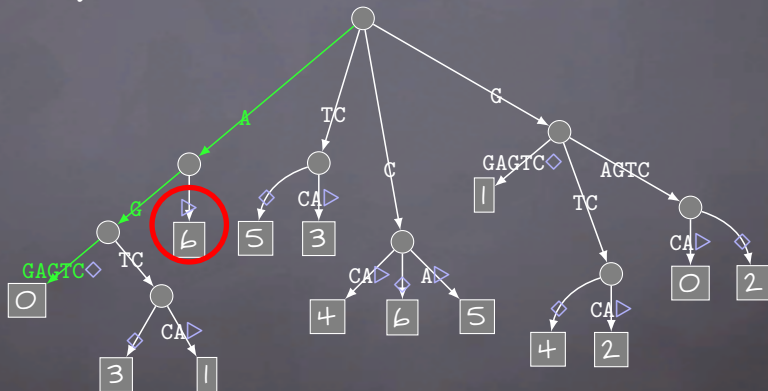
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Overlap-Layout-Consensus Assembly

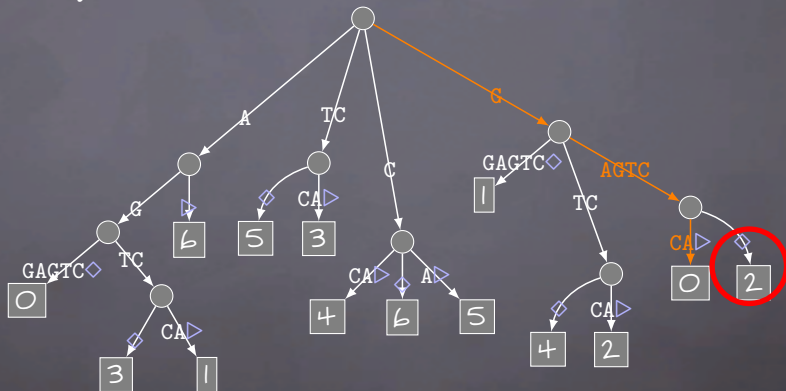
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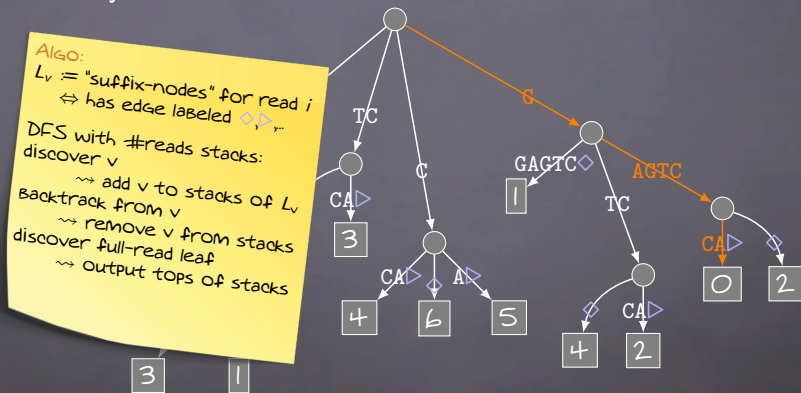
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⇔ $O(\#reads \cdot \text{read-length} + \#reads^2)$

[Gusfield et al.'92]

Overlap-Layout-Consensus Assembly

1. produce pairwise overlaps (All-Pairs Suffix-Prefix)

Fuzzy Overlap – Edit Distance

AGGAGTC

GGTCTCA→

Overlap-Layout-Consensus Assembly

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Overlap-Layout-Consensus Assembly

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GAGTCTCA

Overlap-Layout-Consensus Assembly

1. produce pairwise overlaps (All-Pairs Suffix-Prefix)

Fuzzy Overlap – Edit Distance

AGGAGTC

GAGTCTCA

edit distance = # of insertions, deletions, and substitutions

Overlap-Layout-Consensus Assembly

1. produce pairwise overlaps (All-Pairs Suffix-Prefix)

Fuzzy Overlap – Edit Distance

dynamic programming where

$[i,j]$ = edit distance of $X_{i...} \nleftrightarrow Y_{j...}$

$$= \min\{\boxed{\downarrow} + 1, \boxed{\rightarrow} + 1, \boxed{\searrow} + id_{X_i, Y_j}\}$$

	A	G	G	A	G	T	C	
G								7
G								6
T								5
C								4
T								3
C								2
A								1
	7	6	5	4	3	2	1	0

Overlap-Layout-Consensus Assembly

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	A	G	G	A	G	T	C	
G							6	7
G							5	6
T							4	5
C							3	4
T							2	3
C							1	2
A							1	1
	7	6	5	4	3	2	1	0

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G							6	7
G							5	6
T							4	5
C							3	4
T							2	3
C							1	2
A	6	5	4	3	3	2	1	1
	7	6	5	4	3	2	1	0

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$$= \min\{\boxed{\downarrow} + 1, \boxed{\rightarrow} + 1, \boxed{\searrow} + id_{X_i, Y_j}\}$$

	A	G	G	A	G	T	C	
G	4	3	4	4	4	5	6	7
G	5	4	3	4	3	4	5	6
T	6	5	4	3	3	3	4	5
C	6	5	4	3	2	2	3	4
T	6	5	4	3	2	1	2	3
C	6	5	4	4	3	2	1	2
A	6	5	4	3	3	2	1	1
	7	6	5	4	3	2	1	0

Overlap-Layout-Consensus Assembler

1. produce pairwise overlaps (All-Pairs Suffix-Prefix)

Exercise
Time

Fuzzy Overlap – Edit Distance

dynamic programming where

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$$= \min\{\boxed{\downarrow} + 1, \boxed{\rightarrow} + 1, \boxed{\searrow} + id_{X_i, Y_j}\}$$

	A	G	G	A	G	T	C	
G								○
G								○
T								○
C								○
T								○
C								○
A								○
	1	6	5	4	3	2	1	○

modification: any suffix of GGTCTCA for free



Overlap-Layout-Consensus Assembly

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dynamic programming where

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	A	G	G	A	G	T	C	
G								O
G								O
T								O
C							O	O
T								O
C							O	O
A	6	5	4	3	3	2		O
	7	6	5	4	3	2		O

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G	4	3	2	1	0	1	1	0
T	5	4	3	2	1	0	1	0
C	5	4	3	2	1	1	0	0
T	5	4	3	2	1	0	1	0
C	6	5	4	3	2	1	0	0
A	6	5	4	3	3	2	1	0
	7	6	5	4	3	2	1	0

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	A	G	G	A	G	T	C	
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G	4	3	2	1	0	1	1	0
T	5	4	3	2	1	0	1	0
C	5	4	3	2	1	1	0	0
T	5	4	3	2	1	0	1	0
C	6	5	4	3	2	1	0	0
A	6	5	4	3	3	2	1	0
	7	6	5	4	3	2	1	0

modification: any suffix of GGTCTCA for free

\rightsquigarrow Best overlaps with k errors in $O(\#reads^2 \cdot \text{read-length}^2)$

Overlap-Layout-Consensus Assembly

1. produce pairwise **overlaps** (All-Pairs Suffix-Prefix)
2. **layout** the reads according to the overlaps

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Overlap Graph

reads = vertices

directed edges = overlaps



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⇒ transitive reduction

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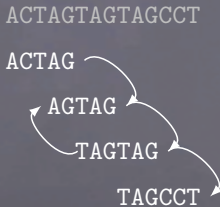
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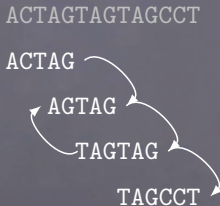
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reads = vertices

directed edges = overlaps



⇒ overlap graph non-linear due to repeats

Overlap-Layout-Consensus Assembly

1. produce pairwise **overlaps** (All-Pairs Suffix-Prefix)
2. **layout** the reads according to the overlaps

Overlap Graph

reads = vertices

directed edges = overlaps

ACTAGTAGTAGCCT

ACTAG

AGTAG

TAGTAG

TAGCCT

⇒ overlap graph **non-linear** due to repeats

⇒ only return non-branching parts ("**contigs**"): ACTAGTAG \neq TAGCCT

Overlap-Layout-Consensus Assembly

1. produce pairwise **overlaps** (All-Pairs Suffix-Prefix)
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3. for each position, compute **consensus** Base

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```
GCCCCTGAACCTTCGCTAGGGTTCTCTAACGACACTCCTTGGGTTTTTACGTCGCGGTTCTCTAGGCCATTGATTGCGGGTCCAGGTGCTGTCAACGAC
GCCCCTGAACCTC          CGACACTCCTTGGGTTTT          CTAGGCCATTGATTGCGGGTC          GGTCCAGGTGCTGTCAACGAC
      ACTTCGC   GGTTCCTC          TCGCTAGGGTTCTCTAACGA          TTTACGTCGCGG          CGAC
```


Overlap-Layout-Consensus Assembly

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GCCCCTGAACCTTCGCTAGGGTTCTCTAACGACACTCCTTGGGTTTTTACGTCGCGGTTCTCTAGGCCATTGATTGCGGGTCCAGGTGCTGTCAACGAC
GCCCCTGAACCTC CGACACTCCTTGGGTTTT CTAGGCCATTGATTGCGGGTC GGTCCAGGTGCTGTCAACGAC
ACTTCGC GGTTCCTC TCGCTAGGGTTCTCTAACGA TTTACGTCGCGG CGAC
GCCCCTGAACCTTCGCTAGGGTTCTCTAACGACACTCCTTGGGTTTTTACGTCGCGG CTAGGCCATTGATTGCGGGTCCAGGTGCTGTCAACGAC

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3. for each position, compute **consensus** Base

Problems

- overlap step too slow in practice:
 10^8 reads $\rightsquigarrow 10^{16}$ read-pairs
 \rightsquigarrow heuristics exclude most of the read-pairs before overlap
- fragmented genome due to repeats

DeBruijn-Graph-Based Assembly

1. chop all reads into "k-mers"
real genomes: $k = 30-50$

DeBruijn-Graph-Based Assembly

1. chop all reads into "**k-mers**"
real genomes: $k = 30-50$
2. Build "**DeBruijn** graph":
for each k-mer add arc from
left to right k-1 mer

Exercise
Time

$k=5$

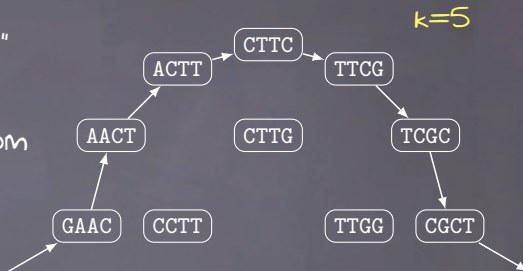


..GAACTTCGCT..

..CCTTGG..

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..**GAACTTCGCT**..

.GAAC

GAACT

AACTT

ACTTC

CTTCG

TTCGC

TCGCT

..**CCTTGG**..

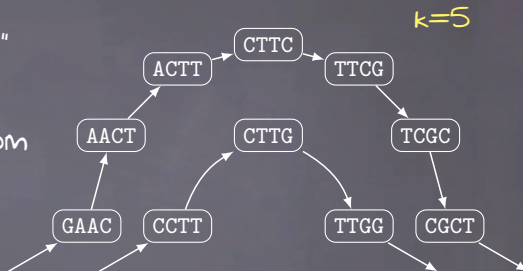
.CCTT

CCTTG

TTGG.

DeBruijn-Graph-Based Assembly

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real genomes: $k = 30-50$
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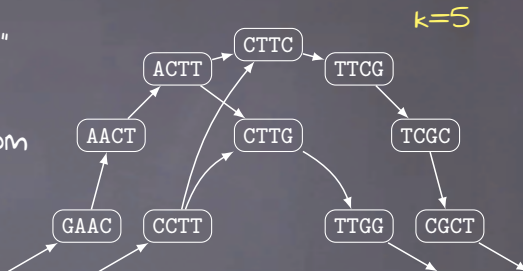
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AACTT

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CTTCG

TTCGC

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CCTTG

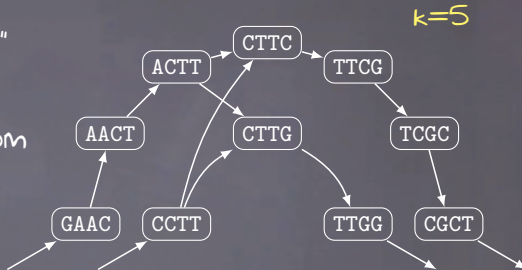
TTGG.

..CCTTC..

..ACTTG..

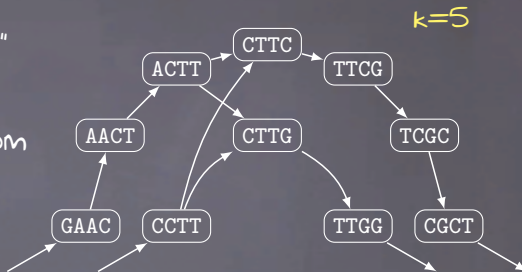
DeBruijn-Graph-Based Assembly

1. chop all reads into "**k-mers**"
real genomes: $k = 30-50$
2. Build "**DeBruijn** graph":
for each k-mer add arc from left to right k-1 mer
3. find path using all overlaps



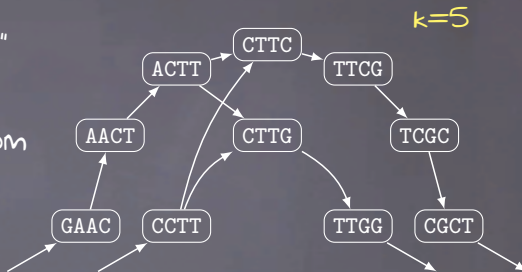
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3. find **Eulerian walk**
linear time with greedy



DeBruijn-Graph-Based Assembly

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Running Time

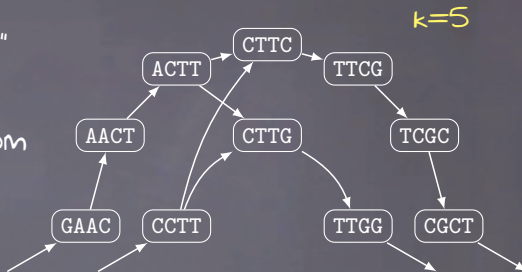
$\#k\text{-mers} = O(\#reads \cdot \text{read-length})$

1. $O(1)$ per k-mer
2. $O(1)$ per k-mer
3. $O(\text{size of graph}) = O(\#k\text{-mers})$

Note: edges can be weighted by $\#occurrences$

DeBruijn-Graph-Based Assembly

1. chop all reads into "**k-mers**"
real genomes: $k = 30-50$
2. build "**DeBruijn** graph":
for each k-mer add arc from left to right k-1 mer
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linear time with greedy



Problems

- choose k well
 - ▶ k too small \rightsquigarrow small repeats become problems
 - ▶ k too big \rightsquigarrow miss smaller overlaps
- Eulerian walk not necessarily unique
- some paths in DeBruijn graph inconsistent with reads
- read-errors problematic
 - \rightsquigarrow error-correction step before assembling
- same problem with repeats as OLC

Correcting Read Errors in Suffix Trees

Example

CAACTTAC

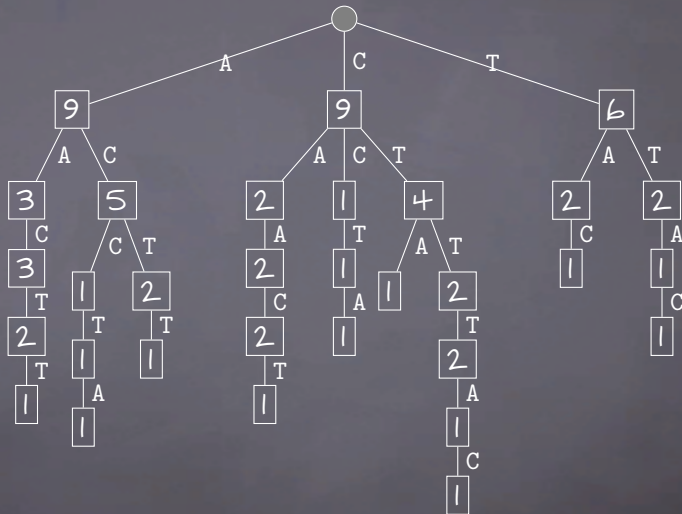
CAACT

CAAC

AACTT

ACCTA

CTTAC



Correcting Read Errors in Suffix Trees

Example

CAACTTAC

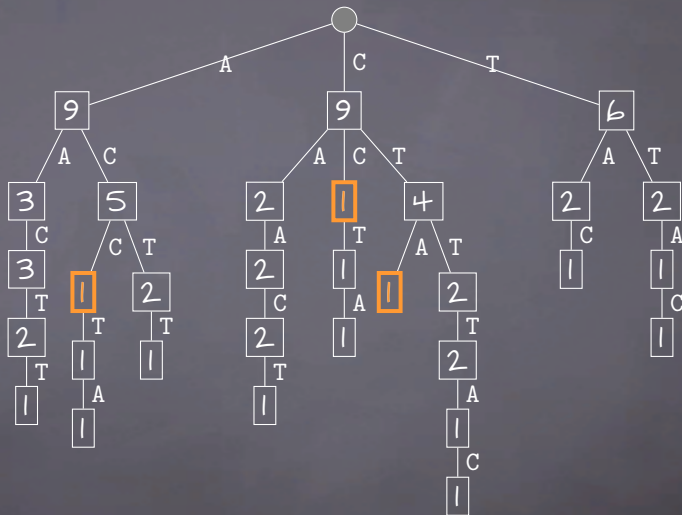
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Idea: low freq. node with high freq. parent \leadsto ignore branch

Correcting Read Errors in Suffix Trees

Example

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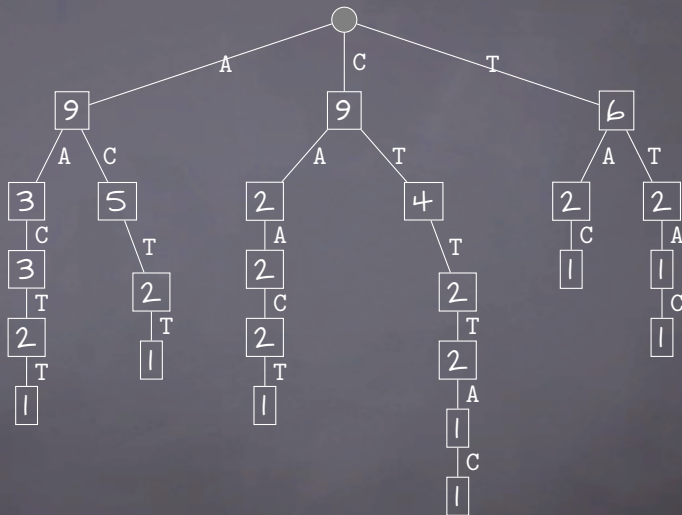
CAACT

CAAC

AACTT

ACCTA

CTTAC



Idea: low freq. node with high freq. parent \leadsto ignore branch

Correcting Read Errors in DBG

Idea

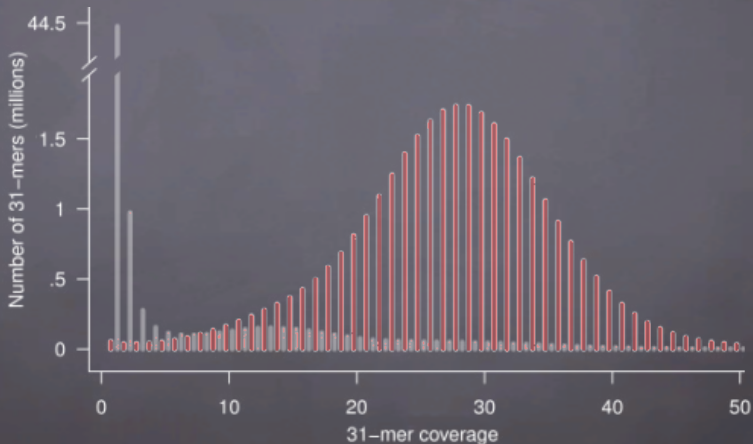
"faulty" k-mers occur less often than correct ones

⇒ Build **k-mer count** histogram

De Bruijn

have to treat errors before building the graph

$k=30 \neq 1\%$ error $\leadsto 1/4$ faulty



Correcting k-mer Errors

Example

suppose: avg. k-mer count = 10 \rightsquigarrow each k-mer occurs about 10x

GCGTATTACGCGTCTGGCCT

CGTATT 8x

GTATTA 9x

TATTAC 7x

ATTACG 12x

TTACGC 9x

TACGCG 9x

ACGCGT 10x

CGCGTC 11x

GCGTCT 10x

CGTCTG 9x

GTCTGG 10x

TCTGGC 10x

CTGGCC 11x

TGGCCT 9x

GCGTATTAC~~T~~CGTCTGGCCT

CGTATT 8x

GTATTA 9x

TATTAC 7x

ATTACT 1x

TTACTC 2x

TACTCG 2x

ACTCGT 1x

CTCGTC 1x

TCGTCT 1x

CGTCTG 9x

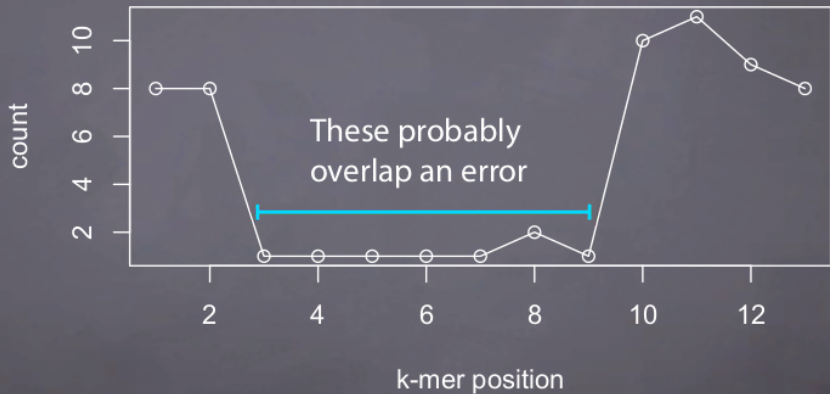
GTCTGG 10x

TCTGGC 10x

CTGGCC 11x

TGGCCT 9x

Correcting k-mer Errors



Correcting k-mer Errors

Problem

now we have an idea where an error is, but how to fix it?

Idea

errors turn frequent k-mers into infrequent ones

~> correction should turn infrequent k-mers into frequent ones

~> replace infrequent k-mer by "frequent neighbor"

Intro: Genome Scaffolding

Recall: repeats (common in DNA) make assembly ambiguous

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~> end product is a set of "contiguous regions"

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~> Scaffolding + Filling

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~> end product is a set of "contiguous regions"

Problem: "contig soup" not very useful

But: with NGS, we have paired-end information!

~> Scaffolding + Filling

Scaffolding

Goal: order & orient contigs

Idea: use pairing information on reads to "link" contigs together

Graph-Based Scaffolding

AACGACACTCCTTGGGTTTTACGTGCGG

GTTAATGTCCGAGCATAAACTCTGGTTGGC

GTACTGAACTTGGGTTCCATAGGACCCAGA

CTAGGCCATTGATTGCGGGTCCAGGTGCTG

AGAGCTTGACAGTAACACATTTAGGAGCACGCG

Graph-Based Scaffolding

AACGACACTCCTTGGGTTTTAGGTGCGG

GTTAATGTCCGAGCATAAACTCTGGTTGGC

GTACTGAACTTGGGTTCCATAGGACCCAGA

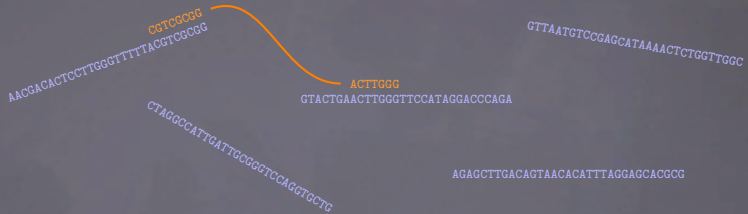
CTAGGCCATTGATTGCGGGTCCAGGTGCTG

AGAGCTTGACAGTAACACATTTAGGAGCACGCG

Strategy

1. map reads into contigs

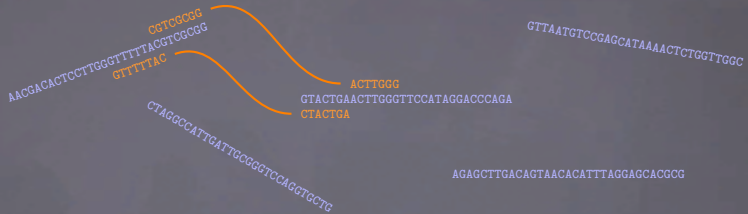
Graph-Based Scaffolding



Strategy

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Graph-Based Scaffolding



Strategy

1. map reads into contigs

Graph-Based Scaffolding

AACGACACTCCTTGGGTTTTAGGTGCGG

GTTAATGTCCGAGCATAAACTCTGGTTGGC

GTACTGAACTTGGGTTCCATAGGACCCAGA

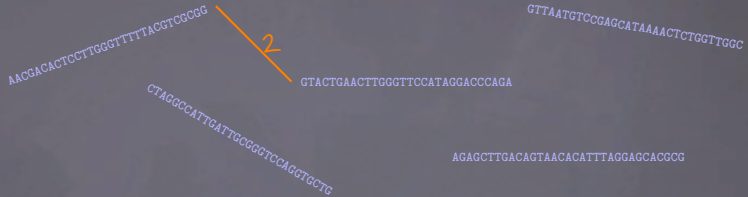
CTAGGCCATTGATTGCGGGTCCAGGTGCTG

AGAGCTTGACAGTAACACATTTAGGAGCACGCG

Strategy

1. map reads into contigs
2. pair contigs according to read-pairing (weighted)

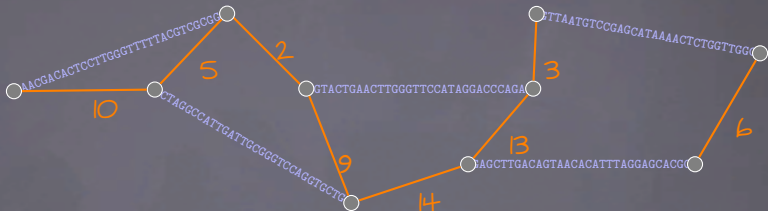
Graph-Based Scaffolding



Strategy

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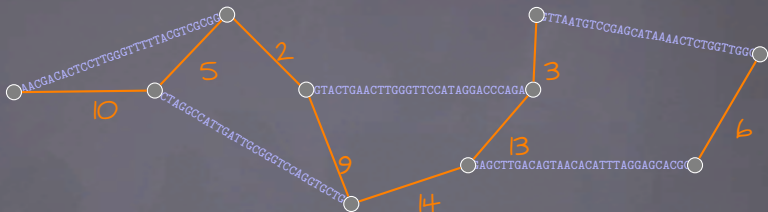
Graph-Based Scaffolding



Strategy

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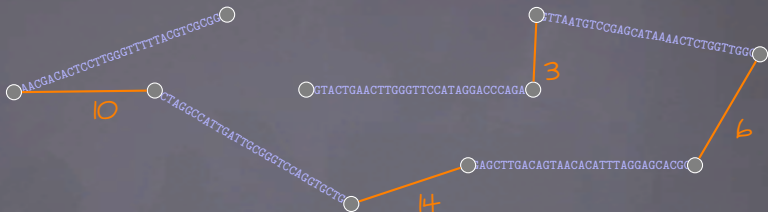
Graph-Based Scaffolding



Strategy

1. map reads into contigs
2. pair contigs according to read-pairing (weighted)
3. cover "scaffold graph" with (heavy) alternating paths
each path corresponds to a chromosome

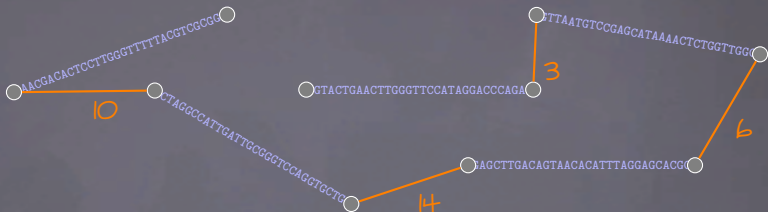
Graph-Based Scaffolding



Strategy

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Graph-Based Scaffolding



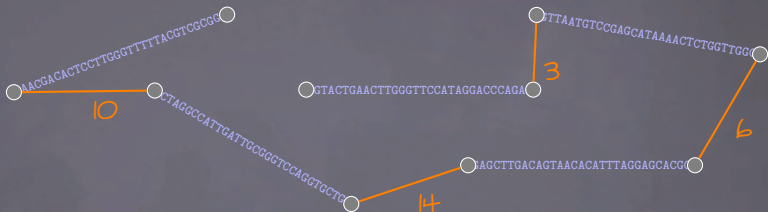
Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $w, k, \sigma_p \in \mathbb{N}$

Question: Can \mathcal{M} be covered by
- $\leq \sigma_p$ alternating paths

of total weight $\geq k$?

Graph-Based Scaffolding



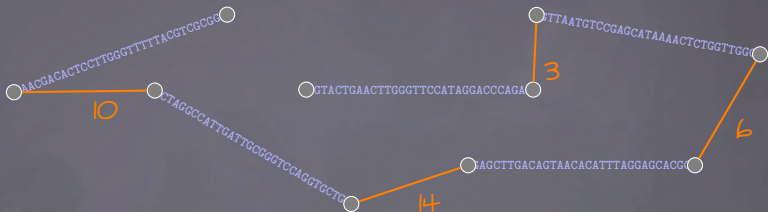
Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can \mathcal{M} be covered by

- $\leq \sigma_p$ alternating paths \nsubseteq
 - $\leq \sigma_c$ alternating cycles
- of total weight $\geq k$?

Graph-Based Scaffolding

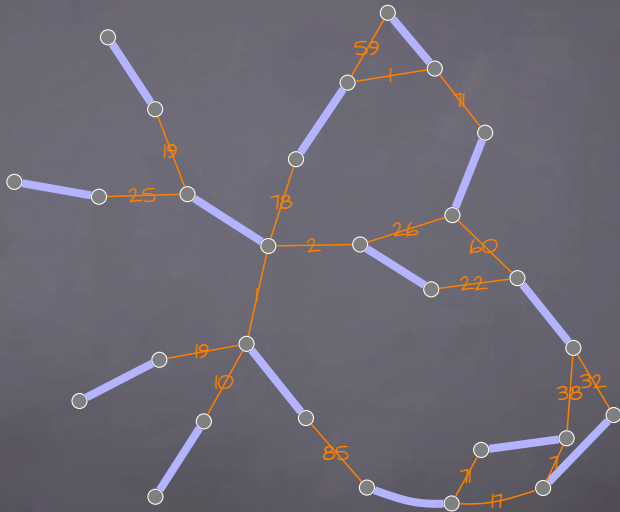


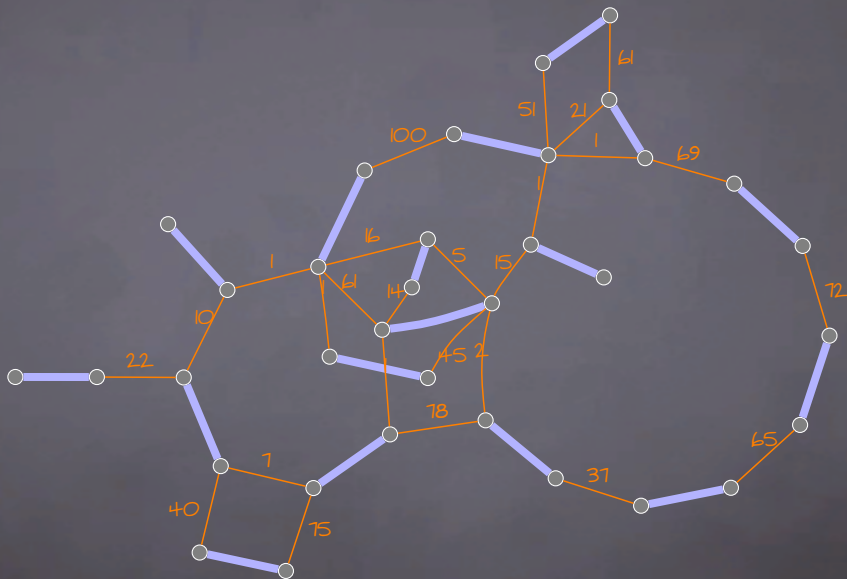
Exact Scaffolding

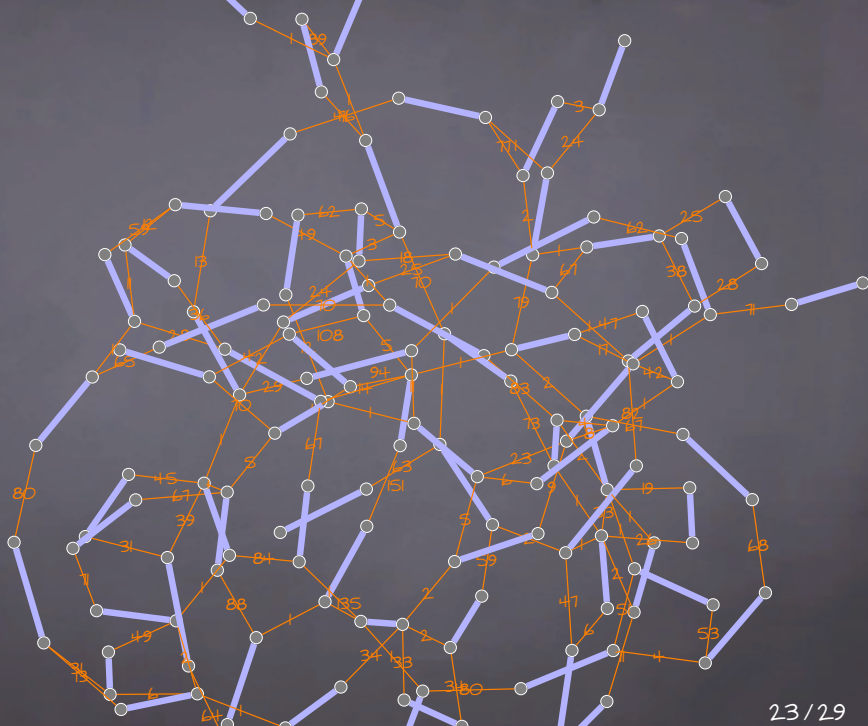
Input: Graph G , perfect matching \mathcal{M} , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can \mathcal{M} be covered by

- σ_p alternating paths \nsubseteq
 - σ_c alternating cycles
- of total weight $\geq k$?





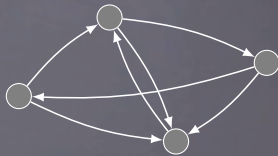
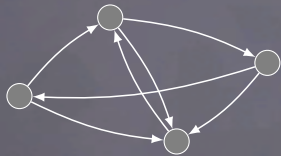


Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can \mathcal{M} be covered by $\leq \sigma_p$ alternating paths \nmid
 $\leq \sigma_c$ alternating cycles of total weight $\geq k$?



Construction

Given a directed graph D

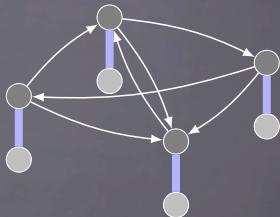
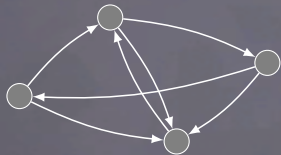
1. make a copy of D

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can \mathcal{M} be covered by $\leq \sigma_p$ alternating paths \nleftrightarrow
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Construction

Given a directed graph D

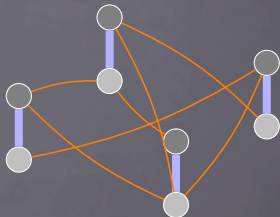
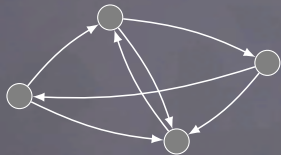
1. make a copy of D
2. duplicate all vertices $\rightsquigarrow \mathcal{M}$

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $w, k, \sigma_p, \sigma_c \in \mathbb{N}$

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Construction

Given a directed graph D

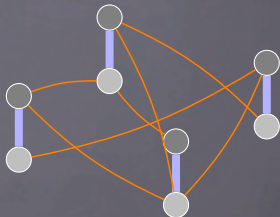
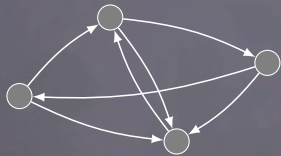
1. make a copy of D
2. duplicate all vertices $\rightsquigarrow \mathcal{M}$
3. "slide" down all arrow tips \nmid ignore directions

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $w, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can \mathcal{M} be covered by $\leq \sigma_p$ alternating paths \neq
 $\leq \sigma_c$ alternating cycles of total weight $\geq k$?



Lemma

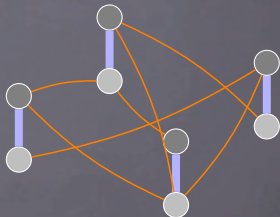
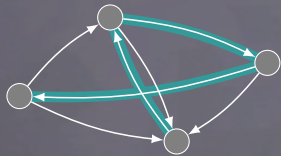
D admits a directed Hamiltonian path $\Leftrightarrow \mathcal{M}$ can be covered with a single alternating path in G

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $w, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can \mathcal{M} be covered by $\leq \sigma_p$ alternating paths \neq
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Lemma

D admits a directed Hamiltonian path $\Leftrightarrow \mathcal{M}$ can be covered with a single alternating path in G

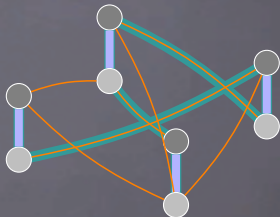
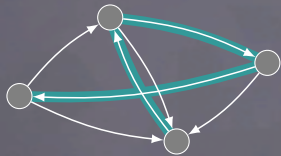
" \Rightarrow ": replace each v in the Hamiltonian path by $v_{\text{low}} \rightarrow v_{\text{high}}$

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching M , weights $w, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can M be covered by $\leq \sigma_p$ alternating paths \neq
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Lemma

D admits a directed Hamiltonian path $\Leftrightarrow M$ can be covered with a single alternating path in G

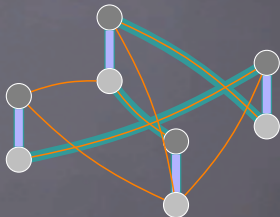
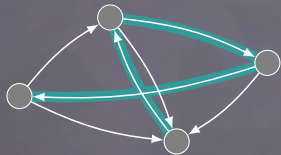
" \Rightarrow ": replace each v in the Hamiltonian path by $v_{\text{low}} \rightarrow v_{\text{high}}$
alternating \checkmark covers M \checkmark

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can \mathcal{M} be covered by $\leq \sigma_p$ alternating paths \neq
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Lemma

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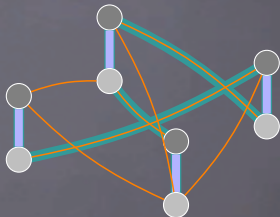
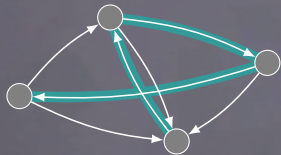
" \Leftarrow ": contract each matching edge in the covering alternating path

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching \mathcal{M} , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

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Lemma

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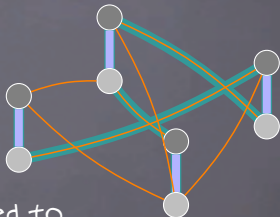
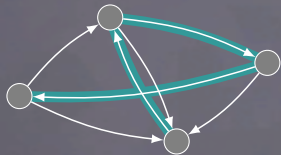
" \Leftarrow ": contract each matching edge in the covering alternating path
hits all vertices exactly once \checkmark is valid directed path \checkmark

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching M , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can M be covered by $\leq \sigma_p$ alternating paths \neq
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Theorem

Scaffolding is NP-hard, even restricted to

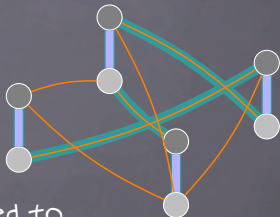
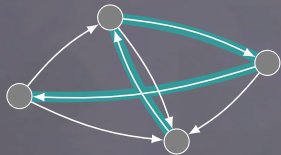
- Bipartite graphs
- $(\sigma_p, \sigma_c) \in \{(0, 1), (1, 0)\}$ and
- $\omega : E \rightarrow \{0\}$

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching M , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can M be covered by $\leq \sigma_p$ alternating paths \neq
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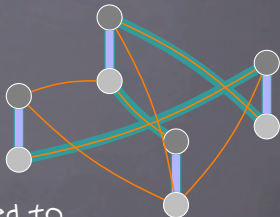
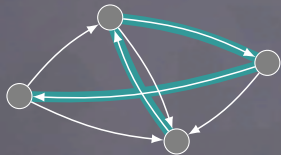
- supergraphs of bipartite graphs
- $(\sigma_p, \sigma_c) \in \{(0, 1), (1, 0)\}$ and
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Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching M , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

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Theorem

Scaffolding is NP-hard, even restricted to

- supergraphs of bipartite graphs
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Corollary

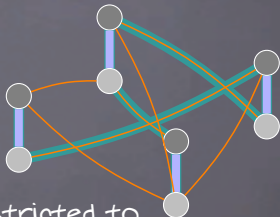
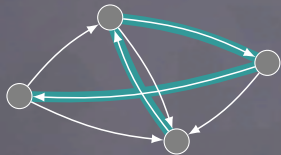
Scaffolding with 2 weights is NP-hard in any sufficiently dense graph class.

Hardness Warm up: Hamiltonian Path

Recall: Scaffolding

Input: Graph G , perfect matching M , weights $\omega, k, \sigma_p, \sigma_c \in \mathbb{N}$

Question: Can M be covered by $\leq \sigma_p$ alternating paths \neq
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Theorem

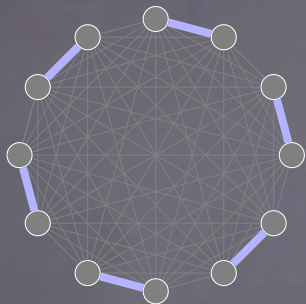
Exact Scaffolding is NP-hard, even restricted to

- supergraphs of bipartite graphs
- $(\sigma_p, \sigma_c) \in \{(0, 1), (1, 0)\}$ and
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Corollary

Exact Scaffolding with 2 weights is NP-hard in any sufficiently dense graph class.

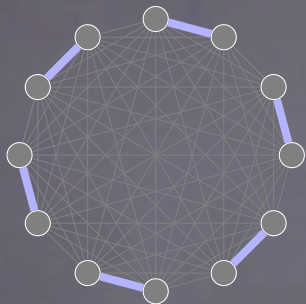
3-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

Approximate Scaffolding

3-Approximation in Dense Graphs

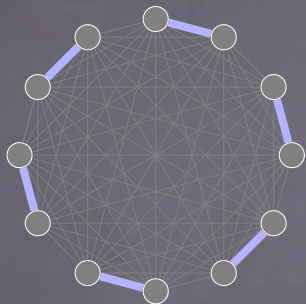


$$\sigma_p = 1, \sigma_c = 1?$$

Approximate Scaffolding

1. sort all edges by weight

3-Approximation in Dense Graphs

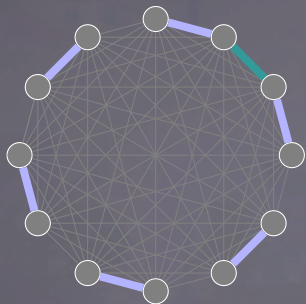


$$\sigma_p = 1, \sigma_c = 1?$$

Approximate Scaffolding

1. sort all edges by weight
2. repeatedly take heaviest poss. edge

3-Approximation in Dense Graphs

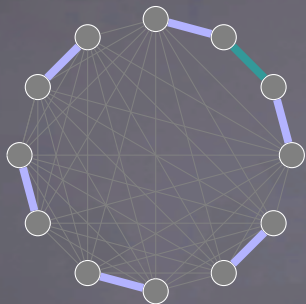


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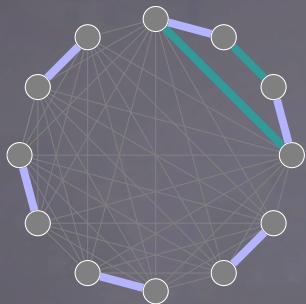


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3-Approximation in Dense Graphs

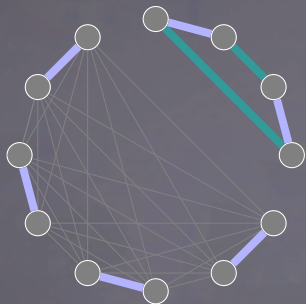


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3-Approximation in Dense Graphs

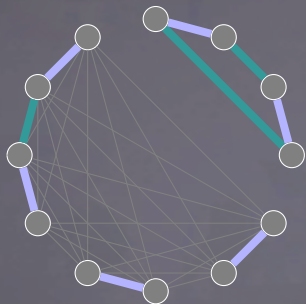


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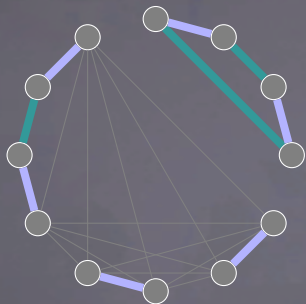


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3-Approximation in Dense Graphs

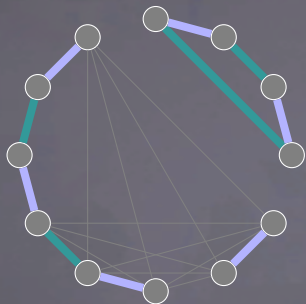


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3-Approximation in Dense Graphs

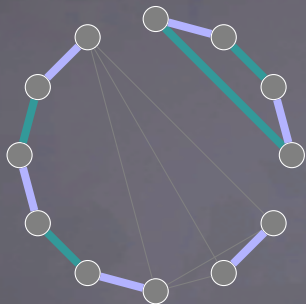


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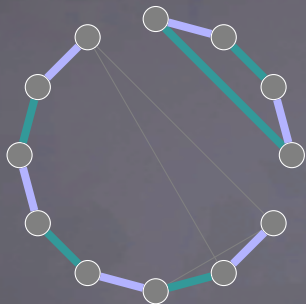


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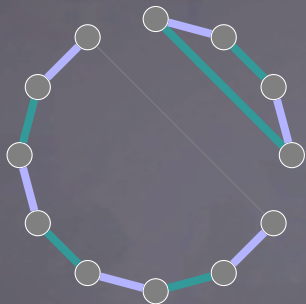


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3-Approximation in Dense Graphs

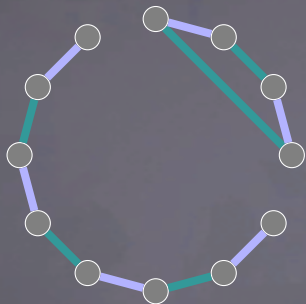


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3-Approximation in Dense Graphs



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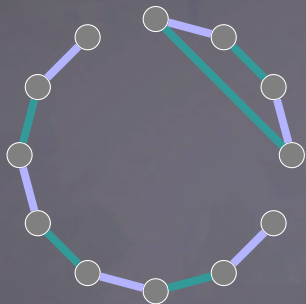
Approximate Scaffolding

1. sort all edges by weight
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Proof

Result S^* is a valid solution ✓

3-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

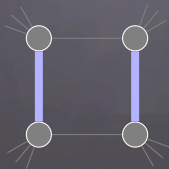
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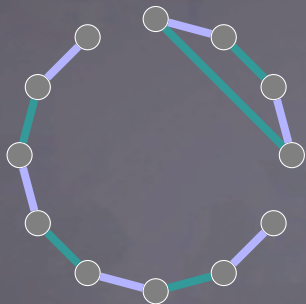
Proof

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Note: taking an edge forbids ≤ 3 OPT edges



3-Approximation in Dense Graphs



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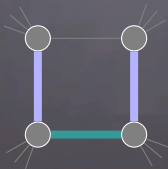
Approximate Scaffolding

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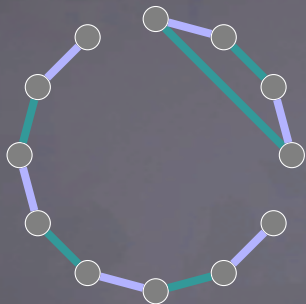
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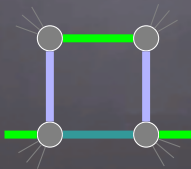
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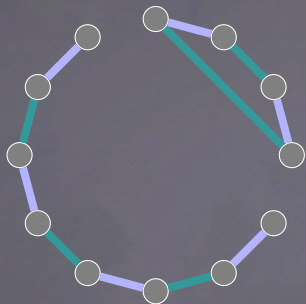
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3-Approximation in Dense Graphs



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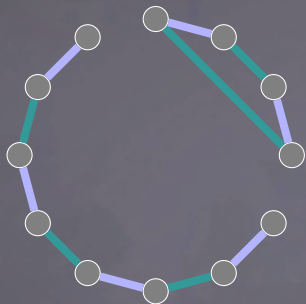
Note: taking an edge forbids ≤ 3 OPT edges

\rightsquigarrow mark the ≤ 3 OPT-edges when taking an edge e

$\rightsquigarrow e$ is heaviest among them

$\rightsquigarrow 3\omega(S^*) \geq OPT$

3-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

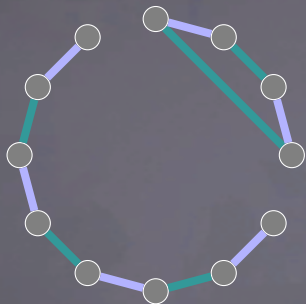
Approximate Scaffolding

1. sort all edges by weight
2. repeatedly take heaviest poss. edge

Theorem

Scaffolding in complete graphs can be 3-approximated in $O(|V|^2 \log |V|)$ time.

3-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

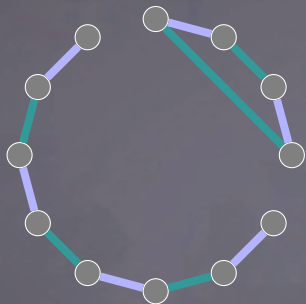
Approximate Scaffolding

1. sort all edges by weight
2. repeatedly take heaviest poss. edge

Theorem

Scaffolding in complete (bipartite) graphs can be 3-approximated in $O(|V|^2 \log |V|)$ time.

3-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

Approximate Scaffolding

1. sort all edges by weight
2. repeatedly take heaviest poss. edge

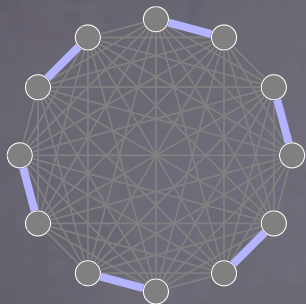
Theorem

Scaffolding in complete (bipartite) graphs can be 3-approximated in $O(|V|^2 \log |V|)$ time.

Remark

For Exact Scaffolding, we have to keep an eye on the number of components too.

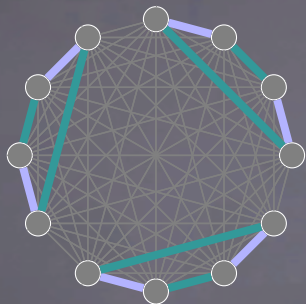
2-Approximation in Dense Graphs



Approximate Scaffolding

$$\sigma_p = 1, \sigma_c = 1?$$

2-Approximation in Dense Graphs



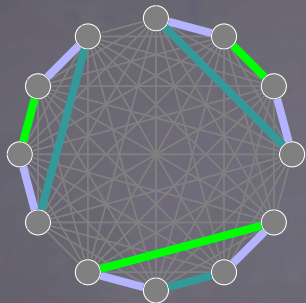
$$\sigma_p = 1, \sigma_c = 1?$$

Approximate Scaffolding

1. compute max-weight perfect matching S

$\rightsquigarrow S \cup M$ is collection of cycles

2-Approximation in Dense Graphs

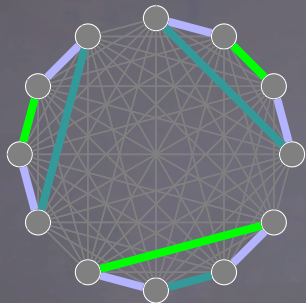


$$\sigma_p = 1, \sigma_c = 1?$$

Approximate Scaffolding

1. compute max-weight perfect matching S
 $\rightsquigarrow S \cup M$ is collection of cycles
2. "fix" all but lightest edge per cycle

2-Approximation in Dense Graphs

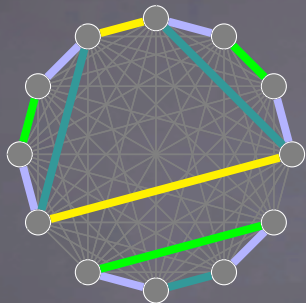


$$\sigma_p = 1, \sigma_c = 1?$$

Approximate Scaffolding

1. compute max-weight perfect matching S
 $\leadsto S \cup M$ is collection of cycles
2. "fix" all but lightest edge per cycle
3. repeatedly flip any lightest non-fix 4-cycle intersecting 2 cycles until at most $\sigma_c + \sigma_p$ cycles remain

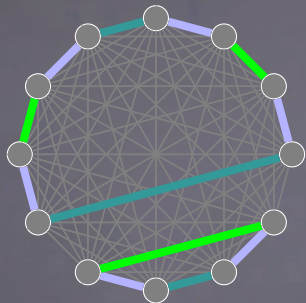
2-Approximation in Dense Graphs



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2-Approximation in Dense Graphs

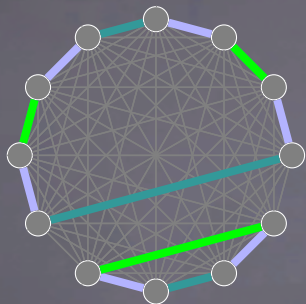


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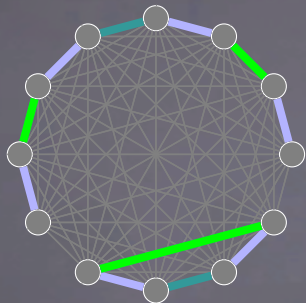
2-Approximation in Dense Graphs



Approximate Scaffolding

1. compute max-weight perfect matching S
 $\rightsquigarrow S \cup M$ is collection of cycles
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4. repeatedly remove lightest non-fix cycle-edge until at most σ_c cycles remain

2-Approximation in Dense Graphs

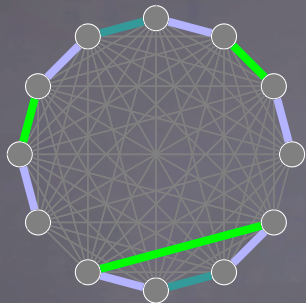


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2-Approximation in Dense Graphs



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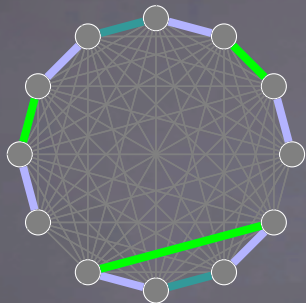
Proof

Result S^* is a valid solution ✓

Approximate Scaffolding

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2-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

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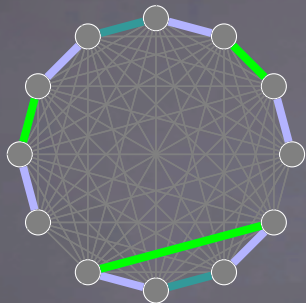
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4. repeatedly remove lightest non-fix cycle-edge until at most σ_c cycles remain

Proof

Result S^* is a valid solution ✓

$$\omega(S^*) \geq \omega(\text{fix}) \geq \omega(S)/2 \geq OPT/2$$

2-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

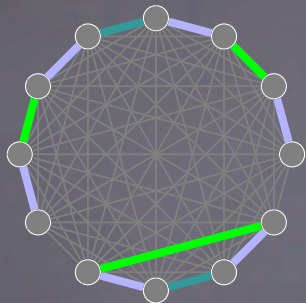
Theorem

Scaffolding in complete graphs can be 2-approximated in $O(|V|^{2.5})$ time.

Approximate Scaffolding

1. compute max-weight perfect matching S
 $\leadsto S \cup M$ is collection of cycles
2. "fix" all but lightest edge per cycle
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2-Approximation in Dense Graphs



$$\sigma_p = 1, \sigma_c = 1?$$

Theorem

Scaffolding in complete (Bipartite) graphs can be 2-approximated in $O(|V|^{2.5})$ time.

Approximate **Scaffolding**

1. compute max-weight **perfect matching** S
 $\leadsto S \cup M$ is collection of cycles
2. "**fix**" all but lightest edge per cycle
3. repeatedly flip any lightest non-**fix** 4-cycle intersecting 2 cycles until at most $\sigma_c + \sigma_p$ cycles remain
4. repeatedly remove lightest non-**fix** cycle-edge until at most σ_c cycles remain

Scaffolding with Multiplicities

Recall: most eucaryotes are diploid!



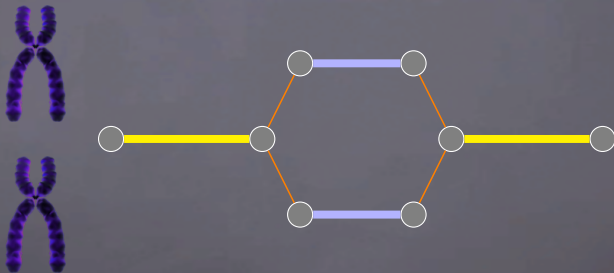
GGTGC**GAGAG**AGGTCATGG**ATTGCAACGA**



GGTGC**GAGAG**GCCACTCCA**ATTGCAACGA**

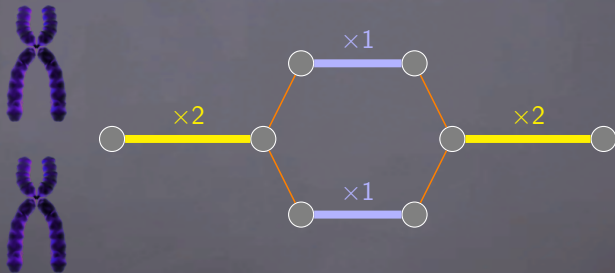
Scaffolding with Multiplicities

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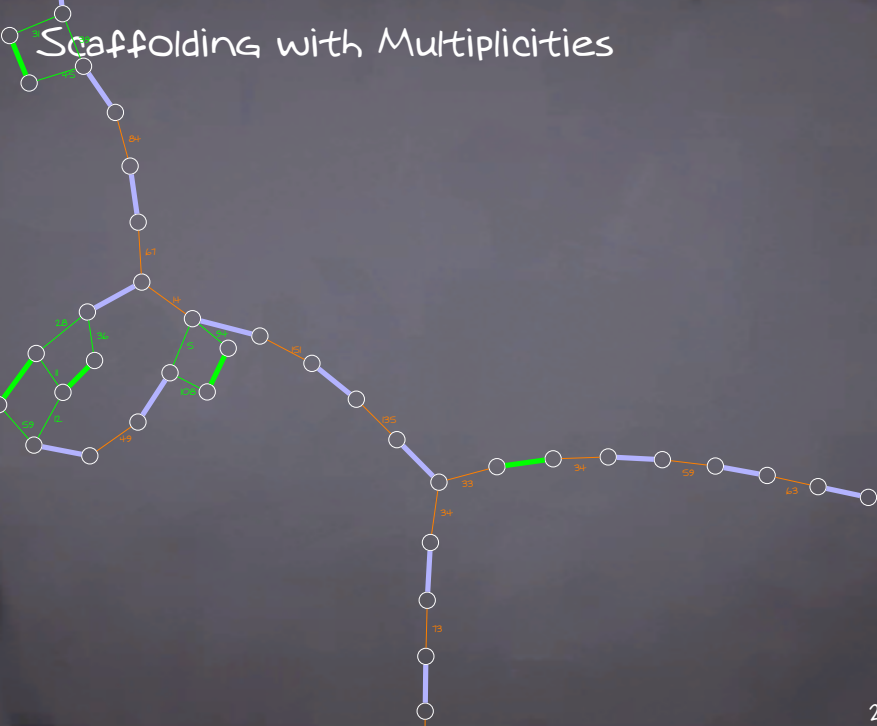


Scaffolding with Multiplicities

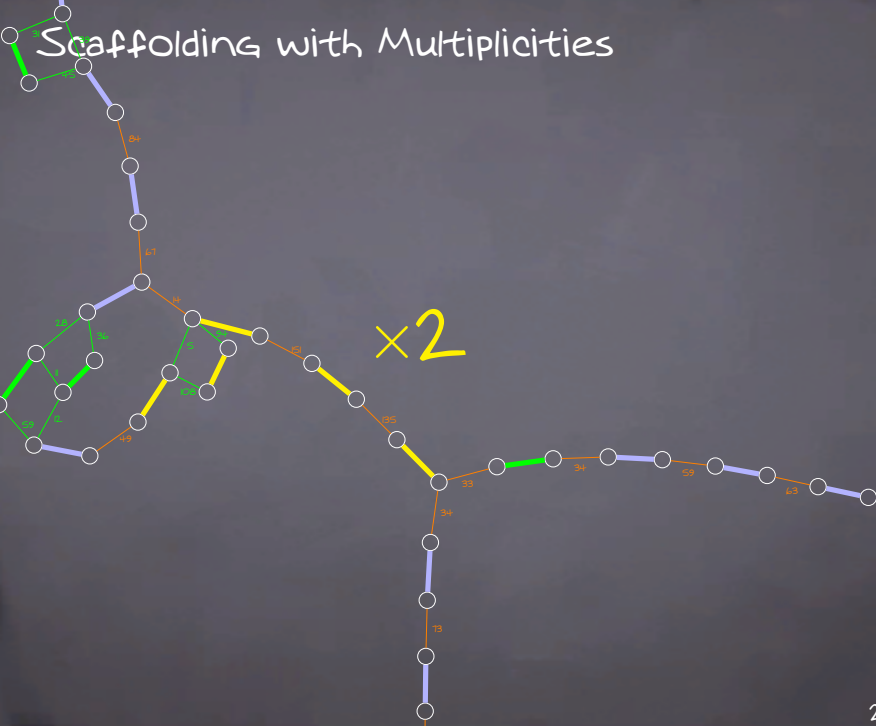
Recall: most eucaryotes are diploid!



Scaffolding with Multiplicities



Scaffolding with Multiplicities



Linearization of Solutions

Problem

no unique chromosome-configuration explaining solution



uniquely linearizable = scaffold graph decomposes uniquely into alternating paths using each edge "the correct" number of times

Linearization of Solutions

Problem

no unique chromosome-configuration explaining solution



uniquely linearizable = scaffold graph decomposes uniquely into alternating paths using each edge "the correct" number of times

Linearization of Solutions

Problem

no unique chromosome-configuration explaining solution



uniquely linearizable = scaffold graph decomposes uniquely into alternating paths using each edge "the correct" number of times

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

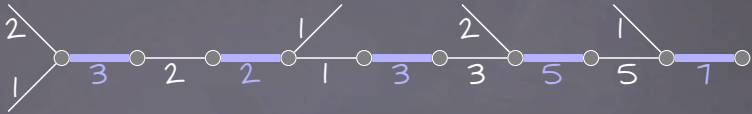
(=alt. path of uniform multiplicity $\mu \nmid$ each end incident to non-contig $< \mu$)

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

(= alt. path of uniform multiplicity $\mu \neq$ each end incident to non-contig $< \mu$)



Linearization of Solutions

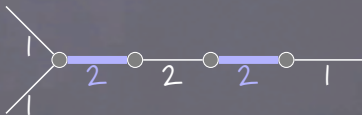
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Proof

" \Rightarrow ": contraposition; let p = ambiguous path



Linearization of Solutions

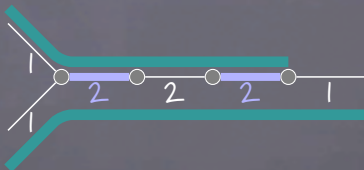
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Linearization of Solutions

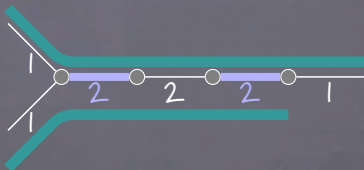
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Linearization of Solutions

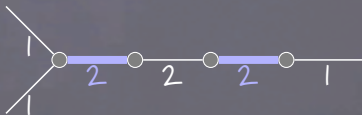
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Proof

" \Rightarrow ": contraposition; let p = ambiguous path



$\leadsto (G, \mathcal{M}, m)$ not uniquely linearizable

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

(=alt. path of uniform multiplicity $\mu \neq$ each end incident to non-contig $< \mu$)

Proof

" \Leftarrow ": let (G, \mathcal{M}, m) be free of ambiguous paths

Reduction (does not decrease number of linearizations):

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

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Linearization of Solutions

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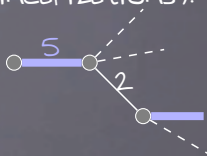
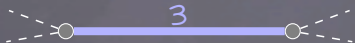
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Linearization of Solutions

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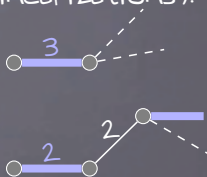
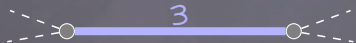
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Reduction (does not decrease number of linearizations):



Linearization of Solutions

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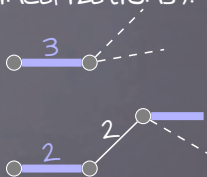
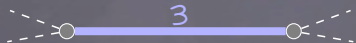
(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

(= alt. path of uniform multiplicity $\mu \nmid$ each end incident to non-contig $< \mu$)

Proof

" \Leftarrow ": let (G, \mathcal{M}, m) be free of ambiguous paths

Reduction (does not decrease number of linearizations):



\leadsto result is collection of alternating paths \nmid cycles

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

(=alt. path of uniform multiplicity $\mu \neq$ each end incident to non-contig $< \mu$)

\rightsquigarrow must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

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Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily

Linearization of Solutions

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\leadsto must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily \leadsto missassembly

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

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 \leadsto must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily \leadsto missassembly
2. isolate each ambiguous path

Linearization of Solutions

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Idea: remove non-matching edges at their endpoints; strategy?

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1. decide arbitrarily \leadsto missassembly
2. isolate each ambiguous path \leadsto information loss

Linearization of Solutions

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(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

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 \leadsto must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily \leadsto missassembly
2. isolate each ambiguous path \leadsto information loss
3. cut as few ends as possible

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

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 \rightsquigarrow must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily \rightsquigarrow missassembly
2. isolate each ambiguous path \rightsquigarrow information loss
3. cut as few ends as possible \rightsquigarrow as hard as Vertex Cover

Linearization of Solutions

Theorem

(G, M, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

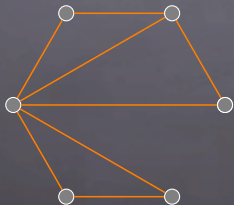
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\leadsto must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; **strategy?**

Proposals

1. decide arbitrarily \leadsto **missassembly**
2. isolate each ambiguous path \leadsto **information loss**
3. cut as few ends as possible \leadsto as hard as **Vertex Cover**



Multiplicities

one \nmid

#non-matching adj. to contig

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

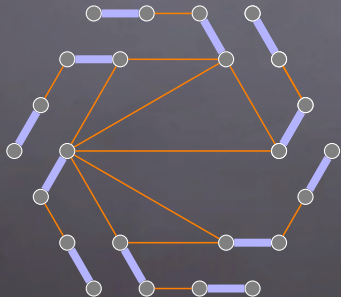
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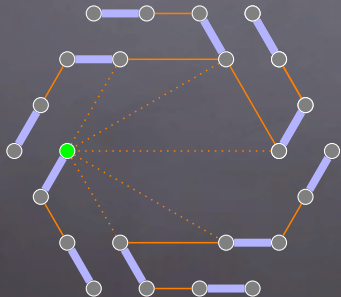
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Linearization of Solutions

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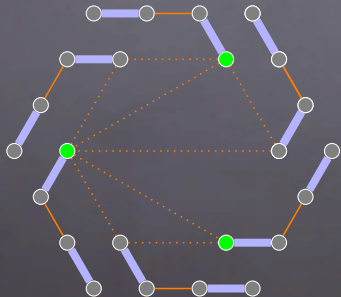
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\leadsto must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

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2. isolate each ambiguous path \leadsto information loss
3. cut as few ends as possible \leadsto as hard as Vertex Cover



Multiplicities

one \nmid

#non-matching adj. to contig

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

(=alt. path of uniform multiplicity $\mu \nmid$ each end incident to non-contig $< \mu$)

\leadsto must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily \leadsto missassembly
2. isolate each ambiguous path \leadsto information loss
3. cut as few ends as possible \leadsto as hard as Vertex Cover
4. cut as few multiplicities as possible

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

(= alt. path of uniform multiplicity $\mu \nmid$ each end incident to non-contig $< \mu$)

\leadsto must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily \leadsto missassembly
2. isolate each ambiguous path \leadsto information loss
3. cut as few ends as possible \leadsto as hard as Vertex Cover
4. cut as few multiplicities as possible \leadsto as hard as Trans. Del. (Δ -free)

Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

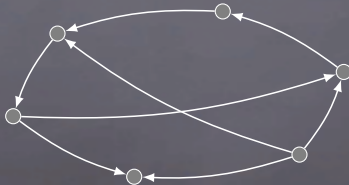
(= alt. path of uniform multiplicity $\mu \nmid$ each end incident to non-contig $< \mu$)

\rightsquigarrow must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; strategy?

Proposals

1. decide arbitrarily \rightsquigarrow missassembly
2. isolate each ambiguous path \rightsquigarrow information loss
3. cut as few ends as possible \rightsquigarrow as hard as Vertex Cover
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Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

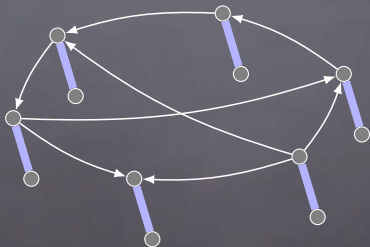
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Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

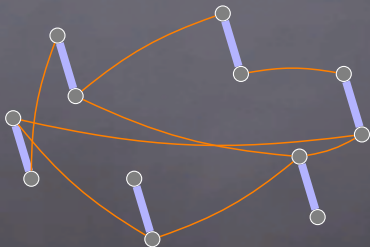
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Linearization of Solutions

Theorem

(G, \mathcal{M}, m) uniquely linearizable \Leftrightarrow no "ambiguous paths"

(= alt. path of uniform multiplicity $\mu \nmid$ each end incident to non-contig $< \mu$)

\rightsquigarrow must destroy ambiguous paths

Idea: remove non-matching edges at their endpoints; **strategy?**

Proposals

1. decide arbitrarily \rightsquigarrow **missassembly**
2. isolate each ambiguous path \rightsquigarrow **information loss**
3. cut as few ends as possible \rightsquigarrow as hard as **Vertex Cover**
4. cut as few multiplicities as possible \rightsquigarrow as hard as **Trans. Del. (Δ -free)**

