Reactive Synthesis of Systems over Data Words

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Example



□ : *G*, "always" ♦ : *F*, "in the future"

 $\Sigma_{\text{in}} = \{ \text{req}_1, \dots, \text{req}_n \}$

 $\Sigma_{\text{out}} = \{\text{grant}_1, \dots, \text{grant}_n\}$

Figure 1. Universal co-Büchi automaton checking that every request is eventually granted.

Figure 2. LTL formula expressing that for each client $c \in \{1, \ldots, n\}$, each of its requests is eventually granted

Known Results

 \rightarrow Target implementation I is a deterministic transducer

Specification	Complexity
Nondeterministic Büchi Automaton	ExpTime-complete (Büchi & Landweber, 1969)
Linear Temporal Logic formula	2-ExpTime-complete (Pnueli & Rosner, 1989)



- \mathcal{D} infinite set of *data*

2 2 3 1 3 1 req req grt req grt grt req ···

Figure 4. A data word with labels $\Sigma = \{req, grt\}$ and data $\mathcal{D} = \mathbb{N}$.

- \rightarrow Large literature on data words:
- Kaminski and Francez, 1994
- Segoufin, 2006
- Bojańczyk, David, Muscholl, Schwentick, and Segoufin, 2011
- Schwentick and Zeume, 2012

- Formula φ to compare incoming data d with register content $\uparrow r$



Figure 5. Universal co-Büchi register automaton checking that every request is eventually granted (the $\varphi = \tau$ tests are omitted).

Test-Free

- Input transitions do not conduct test on data: φ is always T
- Output transitions output the content of some register: φ is always an equality test $d = \uparrow r$.

 \rightarrow The register automaton of Figure 5 is not test-free.

Results

Bounded Synthesis

 \rightarrow The number of registers of the implementation is **fixed**.

Specification (Register Automaton)	Status
Nondeterministic Büchi	Undecidable
Universal co-Büchi	Decidable (Khalimov, Maderbacher, & Bloem, 2018)
	we provide simpler proof techniques

- $\boldsymbol{\varphi}$ a test over input data
- $r_{in} \in R$ register where the input data is stored
- $r_{out} \in R$ register whose content is output



Figure 6. A register transducer immediately granting each request.

Test-Free

- Defined analogously • Transitions are $q \xrightarrow{i \mid \downarrow r_{\text{in}}, o, \uparrow r_{\text{out}}} q'$
- \rightarrow The register transducer of Figure 6 is *test-free*.

Future Work

- Examine the case where the number of registers of the implementation is **not fixed**.
- Synthesise from specifications expressed as **logical formulae**.
- Synthesise from asynchronous specifications and implementations: no strict alternation between input letters and output letters \rightarrow gather information before producing output.
- Relax constraints over the implementation: synthesise an algorithm instead of a transducer (in the

Nondetermir	nistic Test-Free	Decidable	(implementa	tion is al	so Test-Free)	
			-			

Proof Techniques

Reduce to the finite case

- Keep track of equality relations between registers
- Abstract actions by equality types

spirit of Ehlers, Seshia, & Kress-Gazit, 2014)

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