

Projective invariants of vector configurations

Alex Fink, NC State \leftrightarrow MSRI
joint with Andrew Berget, UC Davis \rightarrow U Washington

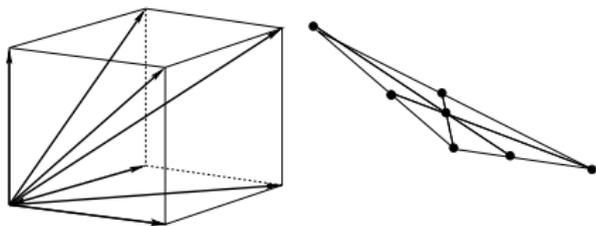
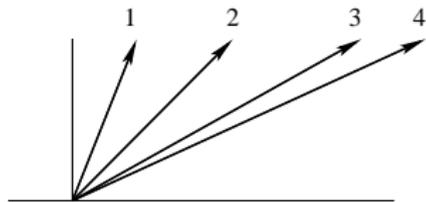
FPSAC, 30 July 2012

Outline of the talk

- Vector configurations & orbits thereof.
- Example: 4 vectors in \mathbb{C}^2 .
- Matroids.
- Equations for $\overline{[v]}$.
- Algebraic invariants.

Vector configurations

A **configuration** is a list $v = (v_1, \dots, v_n)$, where $v_i \in V \approx \mathbb{C}^r$.



The space of configurations is $V \times \dots \times V \approx \mathbb{C}^{r \times n}$.

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 4 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & & 1 & 1 & 1 & 0 \\ & 1 & & 1 & 1 & 0 & 1 \\ & & 1 & 1 & 0 & 1 & 1 \end{bmatrix}$$

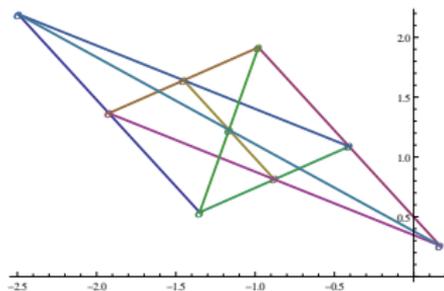
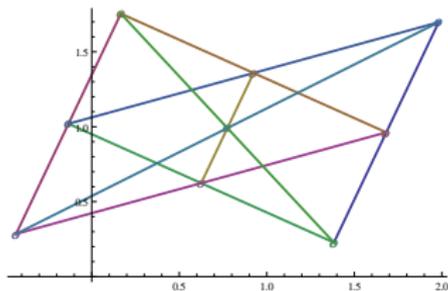
Projective equivalence

The space of r -by- n matrices comes with an action of

$$GL_r \times \underbrace{\prod^n \mathbb{C}^\times}_{=: T^n}$$

(GL_r on the left, T^n on the right.)

Here are two *projectively equivalent* Pappus configurations:



Projective equivalence ctd.

The space of r -by- n matrices comes with an action of

$$GL_r \times \underbrace{\prod^n \mathbb{C}^\times}_{=: T^n}$$

(GL_r on the left, T^n on the right.)

Definition

The projective equivalence class of v is $[v] \subseteq \mathbb{C}^{r \times n}$:

$$[v] := \text{the orbit of } v \text{ under } GL_r \times T^n$$

This set is smooth and locally closed; its closure $\overline{[v]}$ is an irreducible affine variety.

Example. $v \in (\mathbb{C}^{2 \times 4})^o$

Let $v = 4$ non-parallel vectors in \mathbb{C}^2 . There is a unique μ such that

$$\begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & \mu \end{bmatrix} \in [v].$$

This μ is the cross ratio of v :

$$\frac{\det(v_1 v_4) \det(v_2 v_3)}{\det(v_1 v_3) \det(v_2 v_4)} = \mu.$$

Example. $v \in (\mathbb{C}^{2 \times 4})^o$

v is fixed with cross ratio μ

and we may as well choose this v :

$$\mathbf{x} = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 \\ y_1 & y_2 & y_3 & y_4 \end{bmatrix} \quad \text{and} \quad v = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & \mu \end{bmatrix}$$

are equivalent if

$$\frac{\det(\mathbf{x}_1 \mathbf{x}_4) \det(\mathbf{x}_2 \mathbf{x}_3)}{\det(\mathbf{x}_1 \mathbf{x}_3) \det(\mathbf{x}_2 \mathbf{x}_4)} = \mu$$

Example. $v \in (\mathbb{C}^{2 \times 4})^o$

v is fixed with cross ratio μ

and we may as well choose this v :

$$\mathbf{x} = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 \\ y_1 & y_2 & y_3 & y_4 \end{bmatrix} \quad \text{and} \quad v = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & \mu \end{bmatrix}$$

are equivalent if

$$\frac{\det(\mathbf{x}_1 \mathbf{x}_4) \det(\mathbf{x}_2 \mathbf{x}_3)}{\det(\mathbf{x}_1 \mathbf{x}_3) \det(\mathbf{x}_2 \mathbf{x}_4)} = \mu$$

$$(x_1 y_4 - x_4 y_1)(x_2 y_3 - x_3 y_2) - \mu(x_1 y_3 - x_3 y_1)(x_2 y_4 - x_4 y_2) = 0$$

Easy: this single polynomial cuts out $\overline{[v]}$.

(In fact $\overline{[v]}$ has the largest possible dimension.)

On the Combinatorics of linear dependency, H. Whitney (1935).



$$\begin{bmatrix} 1 & & & 1 & 1 & 1 & 0 \\ & 1 & & 1 & 1 & 0 & 1 \\ & & 1 & 1 & 0 & 1 & 1 \end{bmatrix}$$

Record which maximal minors are non-zero, as below:

$$M(v) = \{123, 124, \cancel{125}, 126, \dots, 567\} =: \text{the matroid of } v$$

Points of $[v]$ share a matroid.

The ideal of $\overline{[v]}$

What is the ideal of polynomials in $\mathbb{C}[x_{11}, \dots, x_{rn}]$ that vanish on $\overline{[v]}$?

- What are its generators?

The ideal of $\overline{[v]}$

What is the ideal of polynomials in $\mathbb{C}[x_{11}, \dots, x_{rn}]$ that vanish on $\overline{[v]}$?

- What are its generators?
- What is its Hilbert series?

The ring $\mathbb{C}[x_{11}, \dots, x_{rn}]$ is graded by $\mathbf{N}^r \times \mathbf{N}^n$,

$$\deg x_{ij} = (\mathbf{e}_i, \mathbf{e}_j) \in \mathbf{N}^r \times \mathbf{N}^n$$

and the prime ideal I_v of $\overline{[v]}$ is homogeneous.

Definition.

The **multigraded Hilbert series** $\text{Hilb}(v)$ of $\overline{[v]}$ is the generating function for the dimensions of the $\mathbf{N}^r \times \mathbf{N}^n$ -graded pieces of

$$\mathbb{C}[x_{11}, \dots, x_{rn}] / I_v$$

It is a generating function in variables u_1, \dots, u_r and t_1, \dots, t_n .

Why the Hilbert series?

- $\text{Hilb}(v)$ answers many questions of this form:

Take a subvariety $X \subseteq \mathbb{C}^{r \times n}$ and ask

How many configurations in X are proj. equiv. to v ?

For example: resume $(r, n) = (2, 4)$.

How many configurations of the form

$$\begin{bmatrix} 8 + 12s & 6 + 9s & 9 + 6s & 11 + 14s \\ -3s & -3 + s & -1 - s & -5s + 13 \end{bmatrix}$$

are in $[v]$? Answer: 4. This only depends on the matroid (i.e. on the non-parallel condition.)

Why the Hilbert series?

- $\text{Hilb}(v)$ answers many questions about counting $X \cap \overline{[v]}$.
- It yields info on the irred. decomp. of the S_n -representation spanned by

$$\{v_{w(1)} \otimes v_{w(2)} \otimes \cdots \otimes v_{w(n)} : w \in S_n\}$$

\implies partitions into independent sets [Berget]

- It gives the Tutte polynomial of the matroid. [F-Speyer]

Problems.

- What are the generators of the ideal of $\overline{[v]}$?
- What is its Hilbert series?

Can the answers be determined from $M(v)$?

- Murphy's law suggests "no".
- More convincingly, Mnev's universality thm suggests this too.
- The Grassmannian situation suggests "maybe"...

Gale duality

To get at the ideal of $\overline{[v]}$ we need **Gale duality**.

$$v = \begin{bmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & 1 & 1 & 0 \\ & & & 1 & 1 & 0 & 1 \\ & & & & 1 & 0 & 1 & 1 \end{bmatrix} \rightsquigarrow v^\perp = \begin{bmatrix} -1 & -1 & -1 & 1 & & & & \\ -1 & -1 & 0 & & & 1 & & \\ -1 & 0 & -1 & & & & 1 & \\ 0 & -1 & -1 & & & & & 1 \end{bmatrix}$$

$v^\perp =$ any matrix whose row space forms a basis for $\ker(v)$.

Theorem (Berget–F, 2011)

$$v = \begin{bmatrix} 1 & & 1 & 1 & 1 & 0 \\ & 1 & 1 & 1 & 0 & 1 \\ & & 1 & 0 & 1 & 1 \end{bmatrix}$$

$$\mathbf{x} = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 & x_3 & x_6 & x_7 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_6 & y_7 \\ z_1 & z_2 & z_3 & z_4 & z_5 & z_6 & z_7 \end{bmatrix}$$

Theorem (by example)

The common vanishing locus of the following polynomials is $\overline{[v]}$:

Theorem (Berget–F, 2011)

$$v = \begin{bmatrix} 1 & & 1 & 1 & 1 & 0 \\ & 1 & 1 & 1 & 0 & 1 \\ & & 1 & 0 & 1 & 1 \end{bmatrix} \quad \mathbf{x} = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_6 & y_7 \\ z_1 & z_2 & z_3 & z_4 & z_5 & z_6 & z_7 \end{bmatrix}$$

Theorem (by example)

The common vanishing locus of the following polynomials is $\overline{[v]}$:

Take the 7-by-7 minors of the 12-by-7 matrix

[Kapranov '91]

$$v^\perp \otimes \mathbf{x} = \begin{bmatrix} -1 \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} & -1 \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} & -1 \begin{pmatrix} x_3 \\ y_3 \\ z_3 \end{pmatrix} & \begin{pmatrix} x_4 \\ y_4 \\ z_4 \end{pmatrix} & & & \\ -1 \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} & -1 \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} & \mathbf{0} & & \begin{pmatrix} x_5 \\ y_5 \\ z_5 \end{pmatrix} & & \\ -1 \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} & \mathbf{0} & -1 \begin{pmatrix} x_3 \\ y_3 \\ z_3 \end{pmatrix} & & & \begin{pmatrix} x_6 \\ y_6 \\ z_6 \end{pmatrix} & \\ \mathbf{0} & -1 \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} & -1 \begin{pmatrix} x_3 \\ y_3 \\ z_3 \end{pmatrix} & & & & \begin{pmatrix} x_7 \\ y_7 \\ z_7 \end{pmatrix} \end{bmatrix}$$

AND ...

AND ... for all subconfigurations $v_S \subseteq v$, e.g.,

$$v_{123567}^\perp = \begin{bmatrix} 1 & & 1 & 1 & 0 \\ & 1 & & 1 & 0 & 1 \\ & & 1 & 0 & 1 & 1 \end{bmatrix}$$

take the $|S|$ -by- $|S|$ minors of

$$v_S \otimes \mathbf{x}_S = \begin{bmatrix} -1 \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} & -1 \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} & \mathbf{0} & \begin{pmatrix} x_5 \\ y_5 \\ z_5 \end{pmatrix} \\ -1 \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} & \mathbf{0} & -1 \begin{pmatrix} x_3 \\ y_3 \\ z_3 \end{pmatrix} & \begin{pmatrix} x_6 \\ y_6 \\ z_6 \end{pmatrix} \\ \mathbf{0} & -1 \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} & -1 \begin{pmatrix} x_3 \\ y_3 \\ z_3 \end{pmatrix} & \begin{pmatrix} x_7 \\ y_7 \\ z_7 \end{pmatrix} \end{bmatrix}$$

Comments on the theorem.

- **Conjecture (Berget–F).** The ideal these polynomials generate is prime.

Theorem (Berget–F, 2011). If $r = 2$ or $n = r + 2$ and v has a connected matroid then the conj is true.
In this case, the ideals come out determinantal.

- If v is rank 2 configuration of 4 vectors, recover cross ratio.

$$\det(\mathbf{x}_1\mathbf{x}_4) \det(\mathbf{x}_2\mathbf{x}_3) - \mu \det(\mathbf{x}_1\mathbf{x}_3) \det(\mathbf{x}_2\mathbf{x}_4) = 0$$

Comments on the theorem.

- **Conjecture (Berget–F).** The ideal these polynomials generate is prime.

Theorem (Berget–F, 2011). If $r = 2$ or $n = r + 2$ and v has a connected matroid then the conj is true.
In this case, the ideals come out determinantal.

- If v is rank 2 configuration of 4 vectors, recover cross ratio.

$$\det(\mathbf{x}_1\mathbf{x}_4) \det(\mathbf{x}_2\mathbf{x}_3) - \mu \det(\mathbf{x}_1\mathbf{x}_3) \det(\mathbf{x}_2\mathbf{x}_4) = 0$$

- Dependence on the matroid: the size of v_S^\perp reflects rank v_S .

Details in progress:

The matroid of ν determines $\text{Hilb}(\nu)$, the multigraded Hilbert series of the quotient ring

$$\mathbb{C}[x_{11}, \dots, x_{rn}] / I_\nu.$$

Back to the Hilbert series

Details in progress:

The matroid of v determines $\text{Hilb}(v)$, the multigraded Hilbert series of the quotient ring

$$\mathbb{C}[x_{11}, \dots, x_{rn}] / I_v.$$

Our approach: Compare the variety $\overline{[v]}$ with a torus orbit on the Grassmannian, where we have [F-Speyer].

With Weyman's geometric technique, the comparison is a cohomology computation on toric vector bundles.

$\implies \overline{[v]}$ has rational singularities.

- $r = 2$. For the uniform matroid, by our last theorem:

$$\begin{aligned} \text{Hilb}(v) = & 1 - s_{(2,2)}(u)e_4(t) + s_{(3,2)}(u)e_5(t) \\ & - (2s_{(4,2)}(u) + s_{(3,3)}(u))e_5(t) + \dots \end{aligned}$$

- $r = 2$. For the uniform matroid, by our last theorem:

$$\begin{aligned} \text{Hilb}(v) = & 1 - s_{(2,2)}(u)e_4(t) + s_{(3,2)}(u)e_5(t) \\ & - (2s_{(4,2)}(u) + s_{(3,3)}(u))e_5(t) + \dots \end{aligned}$$

Parallel extensions suffice for every rank 2 configuration.

In equivariant cohomology:

$$\text{class of } \overline{[v]} = \sum_{k=1}^{n/2} \max\{0, \mu'_1 + \dots + \mu'_k - 2k\} s_{(n-k-1,k)}(u)$$

where μ'_k is the number of parallelism classes of $\geq k$ points.

Known cases ctd.

- $r = 2$.
- The uniform matroid, at least in eqvt. cohomology.
- Certain coefficients in an arbitrary configuration:

$$\begin{aligned} \text{Hilb}(v) \equiv 1 - \sum_{D \in \mathcal{D}(M)} s_{(|D| - \text{rk}(D), 1^{\text{rk}(D)})}(u) \prod_{j \in D} t_j \\ \text{mod } \langle s_\lambda(u) : \lambda \text{ not a hook} \rangle + \langle t_1^2, \dots, t_n^2 \rangle, \end{aligned}$$

where $\mathcal{D}(M)$ denotes the dependent sets of the matroid of v .

Thanks for listening!