

ZETA FUNCTIONS OF FINITE-TYPE-DYCK SHIFTS ARE N-ALGEBRAIC

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ABSTRACT. Constrained coding is a technique for converting unrestricted sequences of symbols into constrained sequences, *i.e.* sequences with a predefined set of properties. Regular constraints are described by finite-state automata and the set of bi-infinite constrained sequences are finite-type or sofic shifts. A larger class of constraints, described by sofic-Dyck automata, are the visibly pushdown constraints whose corresponding set of bi-infinite sequences are the sofic-Dyck shifts. An algebraic formula for the zeta function, which counts the periodic sequences of these shifts, can be obtained for sofic-Dyck shifts having a right-resolving presentation. We extend the formula to all sofic-Dyck shifts. This proves that the zeta function of all sofic-Dyck shifts is a computable \mathbb{Z} -algebraic series. We prove that the zeta function of a finite-type-Dyck shift is a computable \mathbb{N} -algebraic series, *i.e.* is the generating series of some unambiguous context-free language. We conjecture that the result holds for all sofic-Dyck shifts.

Zeta function, shift spaces, sofic-Dyck shifts, sofic shifts, visibly pushdown languages, \mathbb{N} -algebraic series

1. INTRODUCTION

Applications of constrained coding are often confined to sequences drawn from regular languages. They are usually described by finite sets of forbidden blocks (finite-type constraints) or by finite-state automata (finite labelled graphs) and are then called sofic constraints since the set of these sequences is a symbolic dynamical system called a sofic shift [33].

Nevertheless, there are classes of constrained sequences going beyond the sofic constraints (see for instance [38], [18]). A particular interesting one is the class of visibly pushdown sequences which corresponds to sofic-Dyck shifts and to visibly pushdown constraints. Visibly pushdown languages [1, 2] are a strict subclass of unambiguous context-free languages. They are rich enough to model many languages like XML languages. They form a natural and meaningful class in between the class of regular languages and the class of unambiguous context-free languages, extending the parenthesis languages [37], [28], the bracketed languages [20], and the balanced languages [10], [11].

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The class of these languages is moreover tractable and robust. For instance the class of visibly pushdown languages over a same pushdown alphabet is stable by intersection and complementation.

In [23], [32], [24], Inoue, Krieger, and Matsumoto introduced and studied special classes of shifts of sequences characterized by a context-free language of factors called Markov-Dyck shifts. They generalize the Dyck shifts whose blocks are finite factors of well parenthesized words. In [24], [30] (see also [22] and [21]), the authors considered also extensions of Markov-Dyck shifts by constructing shifts from sofic systems and Dyck shifts, and shifts defined by \mathcal{R} -graphs. Synchronization properties of Markov-Dyck or Motzkin shifts are obtained in [29], [35], [36], [31].

In [9], we introduced the class of sofic-Dyck shifts which contains the above classes. We showed that they are characterized by a visibly pushdown language. An interesting property of sofic-Dyck constraints is the fact that they have finite-state labelled graph presentations, called Dyck automata, which are equipped with a set of so called matched edges encoding the context-free aspect of the constraints. A subclass of sofic-Dyck shift is the class of finite-type Dyck [8] shifts obtained by adding a finite set of forbidden blocks to some Dyck constraint.

In [9] we performed a computation of the zeta function of a sofic-Dyck shift having a right-resolving presentation. The zeta function is a conjugacy invariant of shifts which counts the periodic sequences (see [3] for an overview of zeta functions). The formula of the zeta function of a shift of finite type is due to Bowen and Lanford [15]. Formulas for the zeta function of a sofic shift were obtained by Manning [34] and Bowen [14]. Proofs of Bowen's formula can be found in [33] and [7, 6]. An \mathbb{N} -rational expression of the zeta function of a sofic shift has been obtained in [39] (see also [12] for zeta functions of formal languages and [25] for the zeta function of periodic-finite-type shifts). The zeta functions of the Dyck shifts were determined by Keller in [26]. For the Motzkin shifts, where some unconstrained symbols are added to the alphabet of a Dyck shift, the zeta function was determined by Inoue in [23]. In [32], Krieger and Matsumoto obtained an expression for the zeta function of a Markov-Dyck shift. The computation in [9] extends Krieger and Matsumoto's formula to sofic-Dyck shifts having a right-resolving presentation.

In this paper, we extend the formula of the zeta function to all sofic-Dyck shifts, getting rid of presentation restrictions. This proves that the zeta function of all sofic-Dyck shifts is a computable \mathbb{Z} -algebraic series. We also prove that the zeta function of a finite-type-Dyck shift is a computable \mathbb{N} -algebraic series, *i.e.* is the generating series of some unambiguous context-free language. Actually, we prove a more precise result. The zeta function of a finite-type Dyck shift is the generating series of a visibly pushdown language, a strict subclass of unambiguous context-free languages. Rational

and algebraic formal power series are well-behaved objects with many interesting properties (see [5, 4], [13], [17], [40]). We conjecture that the zeta function of every sofic-Dyck shift is \mathbb{N} -algebraic.

The paper is organized as follows. In Section 2, we give the definition of the different types of constraints considered in this paper, including the notions of sofic-Dyck shifts and finite-type-Dyck shifts. In Section 3.1 we recall the general formula of the zeta function of a sofic-Dyck which extends the formula of the zeta function of Markov-Dyck shifts from Krieger and Matsumoto [32]. In Section 3.2 we describe how to obtain reduced presentations for sofic-Dyck which have good properties for the computation of the zeta function. In Section 3.3, we recall the formula of the zeta function of a finite-type-Dyck shift obtained in [9]. It was proved in [9] for shifts having a right-resolving presentation and holds now for all finite-type-Dyck shifts. In Section 3.4, we prove the \mathbb{N} -algebraicity of the series. In Section 3.5, we recall the formula of the zeta function of a sofic-Dyck shift obtained in [9]. The restriction on the presentations is removed. We give an example of computation of the series.

2. SOFIC-DYCK CONSTRAINTS

In the section we define the class of finite-type and sofic-Dyck shifts introduced in [9] and [8]. Basic notions of symbolic dynamics can be found in [33, 27].

Let A be a finite alphabet. The set of finite sequences or words over A is denoted by A^* and the set of nonempty finite sequences or words over A is denoted by A^+ . More generally, if L is a set of words over an alphabet A , then L^* is the set of concatenation of words of L , the empty word included.

Let F be a set of finite words over the alphabet A . We denote by X_F the set of bi-infinite sequences of $A^{\mathbb{Z}}$ avoiding each word of F . The set X_F is called a *shift* (or *subshift*). When F can be chosen finite (resp. regular), the shift X_F is called a *shift of finite type* (resp. *sofic*). When F is a visibly pushdown language, the set X_F is called a sofic-Dyck shift [9]. The set of finite factors of a shift X is denoted $\mathcal{B}(X)$, its elements being called *blocks* of X .

Visibly pushdown languages are context-free languages of finite words accepted by visibly pushdown automata defined as follows.

We consider an alphabet A which is partitioned into three disjoint sets of symbols, the set A_c of call symbols, the set A_r of return symbols, and the set A_i of internal symbols. A *visibly pushdown automaton* on finite words over $A = (A_c, A_r, A_i)$ is a tuple $M = (Q, I, \Gamma, \Delta, F)$ where Q is a finite set of states, $I \subseteq Q$ is a set of initial states, Γ is a finite stack alphabet that contains a special bottom-of-stack symbol \perp , $\Delta \subseteq (Q \times A_c \times Q \times (\Gamma \setminus \{\perp\})) \cup (Q \times A_r \times Q \times \Gamma \times Q) \cup (Q \times A_i \times Q)$, and $F \subseteq Q$ is a set of final states. A transition (p, a, q, γ) , where $a \in A_c$ and $\gamma \neq \perp$, is a push-transition. On reading a , the stack symbol γ is pushed onto the stack and the control

changes from state p to q . A transition (p, a, γ, q) is a pop-transition. The symbol γ is read from the top of the stack and popped. If $\gamma = \perp$, the symbol is read but not popped. A transition (p, a, q) is a local action.

A stack is a nonempty finite sequence over Γ ending in \perp . A *run* of M labelled by $w = a_1 \dots a_k$ is a sequence $(p_0, \sigma_0) \cdots (p_k, \sigma_k)$ where $p_i \in Q$, $\sigma_i \in (\Sigma \setminus \{\perp\})^* \perp$ for $1 \leq i \leq k$ and such that:

- If $a_i \in A_c$, then there are $\gamma_i \in \Gamma$ and $(p_{i-1}, a_i, p_i, \gamma_i) \in \Delta$ with $\sigma_i = \gamma_i \cdot \sigma_{i-1}$.
- If $a_i \in A_r$, then there are $\gamma_i \in \Gamma$ and $(p_{i-1}, a_i, \gamma_i, p_i) \in \Delta$ with either $\gamma_i \neq \perp$ and $\sigma_{i-1} = \gamma_i \cdot \sigma_i$ or $\gamma_i = \perp$ and $\sigma_i = \sigma_{i-1} = \perp$.
- If $a_i \in A_i$, then $(p_{i-1}, a_i, p_i) \in \Delta$ and $\sigma_i = \sigma_{i-1}$.

A run is *accepting* if $p_0 \in I$, $\sigma_0 = \perp$, and the last state is final, *i.e.* $p_k \in F$. A word over A is *accepted* if it is the label of an accepting run.

A sofic-Dyck shift is presented by a Dyck-automaton. A *Dyck automaton* over an alphabet $A = (A_c, A_r, A_i)$ is a pair (\mathcal{A}, M) of an automaton (or a directed labelled graph) $\mathcal{A} = (Q, E, A)$ over A where Q is the finite set of states or vertices, $E \subset Q \times A \times Q$ is the set of edges, and with a set M of pairs of edges $((p, a, q), (r, b, s))$ such that $a \in A_c$ and $b \in A_r$. The set M is called the set of *matched edges*. We define the *graph semigroup* S associated to (\mathcal{A}, M) as the semigroup generated by the set $E \cup \{x_{pq} \mid p, q \in Q\} \cup \{0\}$ with the following relations.

$$\begin{array}{ll}
0s = s0 = 0 & s \in S, \\
x_{pq}x_{qr} = x_{pr} & p, q, r \in Q, \\
x_{pq}x_{rs} = 0 & p, q, r, s \in Q, q \neq r, \\
(p, \ell, q) = x_{pq} & p, q \in Q, \ell \in A_i, \\
(p, a, q)x_{qr}(r, b, s) = x_{ps} & (p, a, q), (r, b, s) \in M, \\
(p, a, q)x_{qr}(r, b, s) = 0 & (p, a, q), (r, b, s) \in (A_c \times A_r) \setminus M, \\
(p, a, q)(r, b, s) = 0, & q \neq r, a, b \in A, \\
x_{pp}(p, a, q) = (p, a, q) & p, q \in Q, a \in A, \\
(p, a, q)x_{qq} = (p, a, q) & p, q \in Q, a \in A, \\
x_{pq}(r, a, s) = 0 & a \in A, q \neq r, s \neq t. \\
x(r, a, s)x_{tu} = 0 & a \in A, q \neq r, s \neq t.
\end{array}$$

If π is a finite path of \mathcal{A} , we denote by $f(\pi)$ its image in the graph semigroup S . A finite path π of \mathcal{A} such that $f(\pi) \neq 0$ is said to be an *admissible path* of (\mathcal{A}, M) . A finite word is *admissible* for (\mathcal{A}, M) if it is the label of some admissible path of (\mathcal{A}, M) . A bi-infinite path is *admissible* if all its finite factors are admissible. The *sofic-Dyck shift presented* by (\mathcal{A}, M) is the set of labels of bi-infinite admissible paths of (\mathcal{A}, M) .

A word w labeling an admissible path π such that $f(\pi) = x_{pq}$ for some states p, q is called a *well-matched* word of (\mathcal{A}, M) . It is a *prime Dyck word* if any nonempty shorter prefix of w is not well-matched.

Example 1. Consider the sofic-Dyck shift over A presented by the graph shown in Fig. 1 and with the following matched edges. The $($ -edge is matched with the $)$ -edge and the $[$ -edge is matched with the $]$ -edge. This shift is called the *Motzkin shift*. A sequence is a block (or is allowed) if it is a factor of a well-parenthesized word, the internal letters being omitted. For instance $(i[ii][i])(($ is a block while the patterns $(]$ or $(ii]$ are forbidden. The block $(i[i])$ is a prime well-matched block of the Motzkin shift while $([])($ is a well-matched block which is not prime and $()[[$ is a block which is not well-matched.

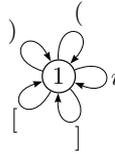


FIGURE 1. The Motzkin shift on the alphabet $A = (A_c, A_r, A_i)$ with $A_c = \{(\, [), A_r = \{), \}\}$ and $A_i = \{i\}$. The $($ -edge is matched with the $)$ -edge and the $[$ -edge is matched with the $]$ -edge.

Example 2. Consider now the sofic-Dyck shift over A presented by the graph shown in Fig. 2 and with the following matched edges. The $($ -edge is matched with the $)$ -edge and the $[$ -edge is matched with the $]$ -edge. This shift is called the *even-Motzkin shift*. The constraint is now stronger than the constraint described by the Dyck-automaton of Example 1. A even number of internal letters i is required between each parenthesis symbol. The even-Motzkin shift is a subshift of the Motzkin shift.

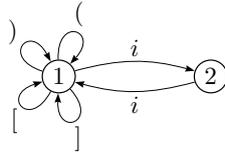


FIGURE 2. The even-Motzkin shift on the alphabet $A = (A_c, A_r, A_i)$ with $A_c = \{(\, [), A_r = \{), \}\}$ and $A_i = \{i\}$. The $($ -edge is matched with the $)$ -edge and the $[$ -edge is matched with the $]$ -edge.

Let a, m be nonnegative integers (m for memory and a for anticipation). A Dyck-automaton (\mathcal{A}, M) is (m, a) -definite if whenever two admissible paths $(p_i, a_i, p_{i+1})_{-m \leq i \leq a}, (q_i, a_i, q_{i+1})_{-m \leq i \leq a}$, of \mathcal{A} of length $m + a$ have the same

label, then $p_0 = q_0$. We say that (\mathcal{A}, M) is *definite* (or *local*) if it is (m, a) -local for some nonnegative integers m and a . Note that this property is independent of the set M . It is shown in [8] that it is not necessary to assume that the paths are admissible. Sofic-Dyck shifts presented by definite Dyck automata are called *finite-type-Dyck shifts*. The Motzkin shift of Example 1 is a finite-type-Dyck shift while the even-Dyck shift of Example 2 is not.

A Dyck-automaton is *right-resolving* (or *deterministic*) if there is at most one edge starting in a given state and with a given label. Sofic shifts (see [33]) have right-resolving presentations. It is no more the case in general for sofic-Dyck shifts although visibly pushdown languages are accepted by deterministic visibly pushdown automata [1].

3. ZETA FUNCTIONS OF SOFIC-DYCK SHIFTS

In this section, we recall the formula of the zeta function of a sofic-Dyck shift obtained in [9]. This formula was established for shifts having a right-resolving Dyck automaton. We extend the formula to all sofic-Dyck shifts.

3.1. Definitions and general formula. We first define the *multivariate zeta function* of a shift. Denote $\mathbb{Z}\langle\langle A \rangle\rangle$ the set of noncommutative formal power series over \mathbb{Z} on the alphabet A . Each language L of finite words over A defines a series, its characteristic series defined by $\underline{L} = \sum_{u \in L} u$.

Let $\mathbb{Z}[[A]]$ be the usual commutative algebra of formal power series in the variables a in A and $\pi: \mathbb{Z}\langle\langle A \rangle\rangle \rightarrow \mathbb{Z}[[A]]$ be the natural homomorphism. Let $S \in \mathbb{Z}\langle\langle A \rangle\rangle$ be a noncommutative series. One can write $S = \sum_{n \geq 0} [S]_n$ where each $[S]_n$ is the homogeneous part of S of degree n . The *multivariate zeta function* of S is the commutative series in $\mathbb{Z}[[A]]$ is

$$Z(S) = \exp \sum_{n \geq 1} \frac{[S]_n}{n}.$$

The (*ordinary*) *zeta function* of a language L is

$$\zeta_L(z) = \exp \sum_{n \geq 1} a_n \frac{z^n}{n},$$

where a_n is the number of words of lengths n of L . Note that $\zeta_L(z) = \theta(Z(\underline{L}))$, where $\theta: \mathbb{Z}[[A]] \rightarrow \mathbb{Z}[[z]]$ is the homomorphism such that $\theta(a) = z$ for any letter $a \in A$.

Let X be a shift. The set X is invariant by the *shift transformation* σ defined by $\sigma((x_i)_{i \in \mathbb{Z}}) = (x_{i+1})_{i \in \mathbb{Z}}$. Call *periodic pattern* of X a word u such that the bi-infinite concatenation of u belongs to X and denote $P(X)$ the set of periodic patterns of X . These definitions are extended to σ -invariant sets of bi-infinite sequences which may not be shifts (*i.e.* which may not be closed subsets of sequences).

The *multivariate zeta function* $Z(X)$ of the shift (resp. *zeta function* $\zeta_X(z)$ of the shift) X is defined as the multivariate zeta function (resp. zeta

function) of its set of periodic patterns. Hence

$$\zeta_X(z) = \exp \sum_{n \geq 1} p_n \frac{z^n}{n},$$

where p_n the number of points of X of period n , *i.e.* of points x such that $\sigma^n(x) = x$.

Let X be a sofic-Dyck shift presented by a Dyck automaton (\mathcal{A}, M) over A , where Q is the set of states.

We denote by X_C the σ -invariant subset of X containing all orbits of points obtained by bi-infinite concatenation of prime Dyck words. We denote by X_{C_c} (resp. X_{C_r}) the σ -invariant subset of X containing all orbits of points obtained by bi-infinite concatenation of words of the form uv , where u is a prime Dyck word and $v \in A_c^*$ (resp. of words of the form vu , where u is a prime word and $v \in A_r^*$). We also denote by X_{Z_c} (resp. X_{Z_r}) the subshifts of X of points included in $A_c^{\mathbb{Z}}$ (resp. in $A_r^{\mathbb{Z}}$).

The following proposition is due to Krieger and Matsumoto [32] for Markov-Dyck shifts. It extends to sofic-Dyck shifts directly [9].

Proposition 1. *The zeta function $\zeta_X(z)$ of a sofic-Dyck shift satisfies*

$$(1) \quad \zeta_X(z) = \frac{\zeta_{X_{C_c}}(z)\zeta_{X_{C_r}}(z)\zeta_{X_{Z_c}}(z)\zeta_{X_{Z_r}}(z)}{\zeta_{X_C}(z)},$$

where $X_C, X_{C_c}, X_{C_r}, X_{Z_c}, X_{Z_r}$ are the σ -invariant subsets of subshifts defined above.

3.2. Reduced presentations of sofic-Dyck shifts. In order to compute the zeta functions of Equation (1), we need to work with presentations of a sofic-Dyck shift for which some good properties hold, as for instance deterministic or unambiguous Dyck automata.

A Dyck automaton is said to be *unambiguous* if whenever two *admissible* paths with the same origin, end, and label are equal.

Sofic-Dyck shifts may not have either deterministic or unambiguous presentations in general. We show below that the determinization (or co-determinization) process of visibly pushdown automata [1] can be adapted to Dyck automata and performs a *reduction* of these automata.

Let (\mathcal{A}, M) be a Dyck automaton accepting a sofic-Dyck shift X . Following the subset-based construction of [1] we define the Dyck automaton (\mathcal{A}, N) as follows. The process has some similarity with the determinization of transducers. We refer to [1, Theorem 2] for the intuition of the construction.

If $\mathcal{A} = (Q, E, A)$, we first define the Dyck automaton $\mathcal{T} = (\mathfrak{P}(Q \times Q) \times \mathfrak{P}(Q), F, B)$ where $B = (A_c \times (\mathfrak{P}(Q \times Q) \times \mathfrak{P}(Q) \times A_c), A_r \times ((\mathfrak{P}(Q \times Q) \times \mathfrak{P}(Q) \times A_r) \cup \{\perp\}), A_i$, and $\mathfrak{P}(S)$ is the set of subsets of S for a set S .

A set S called the summary is associated to each state p . If p can be reached after reading aw , where a is a call letter and w a well-matched

word, the summary of p contains pairs of states (q, q') such that there is an admissible path from q to q' in (\mathcal{A}, M) labelled by w .

Let $\text{Diag}(Q)$ denote the set of all pairs (p, p) for $p \in Q$.

The edges of \mathcal{T} are defined as follows.

- For every $\ell \in A_i$, $((S, R), \ell, (S', R')) \in F$ if $S' = \{(p, p') \mid \exists q \in Q: (p, q) \in S, (q, \ell, p') \in E\}$ and $R' = \{p' \mid \exists p \in P: (p, \ell, p') \in E\}$.
- For every $a \in A_c$, $((S, R), a \mid (S, R, a), (\text{Diag}(Q), R')) \in F$ if $R' = \{p' \mid \exists p \in R: (p, a, p') \in E\}$.
- For every $b \in A_r$, $((S, R), b \mid (S'', R''), a), (S', R') \in F$ if $S' = \{(p, p') \mid \exists p_3: (p, p_3) \in S'', (p_3, p') \in \text{Update}\}$ is non empty and $R' = \{p' \mid \exists p \in R'': (p, p') \in \text{Update}\}$, where Update is $\{(p, p') \mid \exists p_1, p_2: (p, a, p_1) \in E, (p_1, p_2) \in S, (p_2, b, p') \in E, ((p, a, p_1), (p_2, b, p')) \in M\}$.
- For every $b \in A_r$, $((S, R), b \mid \perp, (\emptyset, R')) \in F$ if (S', R') are as in the previous item and S' is empty.

The Dyck automaton (\mathcal{B}, N) is obtained as follows. The automaton \mathcal{B} is obtained from \mathcal{T} by removing the second components of the labels of edges of \mathcal{T} . Every return edge $((S, R), b, (S', R'))$ such that $((S, R), b \mid (S'', R''), a), (S', R') \in F$ in \mathcal{T} is matched with every call edge labelled by a and starting at (S'', R'') . Note that there is at most one edge with a given label between two given states in \mathcal{B} . The Dyck automaton (\mathcal{B}, N) is called the *left reduction* of (\mathcal{A}, N) and is said to be *left reduced*. We similarly define the *right reduction* of (\mathcal{A}, N) with a co-determinization of (\mathcal{A}, N) and an inversion of the roles played by call and return edges.

The determinization process is shown in Fig. 3.

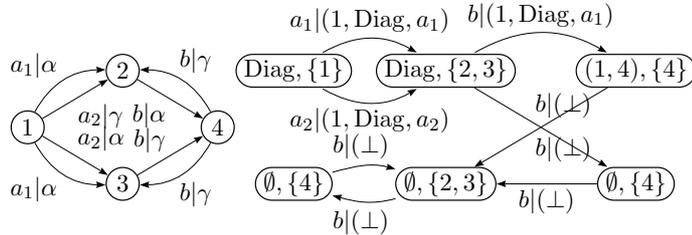


FIGURE 3. The left-reduction of the Dyck automaton (\mathcal{A}, M) over $A = (\{a\}, \{b\}, A_i)$ pictured on the left. The labels of edges of (\mathcal{A}, M) are the first components of the edges of the picture. Two call and return edges are matched if they share the same second-component label. The Dyck automaton \mathcal{T} is pictured on the right. The left-reduction of (\mathcal{A}, M) is obtained by removing the second components of the labels of \mathcal{T} .

A Dyck automaton is said to be *well-matched deterministic* (resp. *L-deterministic*) if any two finite admissible paths labelled by a same well-matched word (resp. a word in a language L) and with the same origin have the same end.

Proposition 2. *A left-reduced Dyck automaton presenting a sofic-Dyck shift X with set of blocks $\mathcal{B}(X)$ is L -deterministic when L is either the code $C(X)$ of prime Dyck words of X , or the set $C(X)(A_c)^* \cap \mathcal{B}(X)$, or the set $(A_c)^* \cap \mathcal{B}(X)$. A right-reduced Dyck automaton presenting a sofic-Dyck shift X with set of blocks $\mathcal{B}(X)$ is L -codeterministic when L is either the set $(A_r)^* C(X) \cap \mathcal{B}(X)$, or $(A_r)^* \cap \mathcal{B}(X)$.*

Proof. Let (\mathcal{A}, M) be a left-reduced Dyck automaton. By construction, (\mathcal{A}, M) is $((A_c)^* \cap \mathcal{B}(X))$ -deterministic.

Let us show that (\mathcal{A}, M) is L -deterministic, where L is the set of well-matched words of $\mathcal{B}(X)$. Assume the contrary, let w be a shortest well-matched word for which there are two admissible paths of (\mathcal{A}, M)

$$\begin{aligned} p &\xrightarrow{a} p_1 \xrightarrow{u} q_1 \xrightarrow{b} r_1 \xrightarrow{v} s_1, \\ p &\xrightarrow{a} p_2 \xrightarrow{u} q_2 \xrightarrow{b} r_2 \xrightarrow{v} s_2, \end{aligned}$$

such that $a \in A_c$, $b \in A_r$ and u, v are well-matched words.

We first have $p_1 = p_2$. By assumption, we get $q_1 = q_2$. If $r_1 = (S'_1, R'_1) \neq r_2 = (S'_2, R'_2)$, and $q_1 = (S, R)$, there are two edges $((S, R), b|(S''_1, R''_1, a_1), (S'_1, R'_1))$ and $((S, R), b|(S''_2, R''_2, a_2), (S'_2, R'_2)) \in \mathcal{T}$. Since the above paths are admissible, these two edges have to be matched with $(p = (S'', R''), a, p_1)$. It follows that $(S''_1, R''_1, a_1) = (S''_2, R''_2, a_2)$ and $r_1 = r_2$. Again by assumption, $s_1 = s_2$.

The fact that (\mathcal{A}, M) is L -deterministic, where L is the set $C(X)(A_c)^* \cap \mathcal{B}(X)$ follows easily. \square

If (\mathcal{A}, M) is definite, then its left and right reduction are also definite.

3.3. Zeta function of finite-type-Dyck shifts. In the rest of the paper, we will assume that (\mathcal{A}, M) is a left-reduced Dyck automaton and (\mathcal{A}', M') is a right-reduced Dyck automaton accepting a sofic-Dyck shift X .

We define the matrix $C = (C_{pq})_{p,q \in Q}$ in $(Q \times Q)^{\mathbb{Z}\langle\langle A \rangle\rangle}$ where C_{pq} is the characteristic series of the set of prime Dyck words labeling an admissible paths of (\mathcal{A}, M) going from p to q . We denote by M_c the matrix in $(Q \times Q)^{\mathbb{Z}\langle\langle A_c \rangle\rangle}$ where $M_{c,pq}$ is the characteristic series of the set of labels of paths going from p to q and made only of consecutive edges of \mathcal{A} labelled by call letters. We define C' and M_r similarly for (\mathcal{A}', M') . We denote by C_c (resp. C_r) the matrix $C M_c^*$ (resp. $M_r^* C'$). We denote by X_H be the σ -invariant set containing all orbits of points $x \in A^{\mathbb{Z}}$ which are labels of bi-infinite paths of $(p_i, c_i, p_{i+1})_{i \in \mathbb{Z}}$, where $c_i \in H_{p_i p_{i+1}}$. Note that $X_{M_c} = X_{C_c}$ and $X_{M_r} = X_{C_r}$.

By Proposition 2, each matrix $H = C, C_c, M_c$ has 0–1 coefficients and the product of H by H is *unambiguous*, i.e. if for each word $uv \in H_{pq}$, there is a unique state r such that $u \in H_{pr}$ and $v \in H_{rq}$. This is equivalent to the fact that H^k has 0–1 coefficients for any $k \geq 0$. The same results holds for $H = C', C_r, M_r$.

We denote by H_σ the matrix such that $H_{\sigma,pq} = \sum_{w \in H_{pq}} \sum_{1 \leq j \leq |w|} \sigma^j(w)$, where $\sigma(a_1 \dots a_n) = a_2 \dots a_n a_1$.

Proposition 3. *Let (\mathcal{A}, M) be a left reduced definite Dyck automaton and H be one of the matrices C, C_c, M_c in $(Q \times Q)^{\mathbb{Z}\langle\langle A \rangle\rangle}$ defined above. We have*

$$\begin{aligned} \pi(\underline{P}_n(\mathbf{X}_H)) &= \text{tr}[\pi H_\sigma(1 - \pi H)^{-1}]_n, \\ &= \text{tr} \sum_{1 \leq j \leq n} j[\pi(H)]_j[(1 - \pi H)^{-1}]_{n-j}. \end{aligned}$$

where $P_n(\mathbf{X}_H)$ is the set of periodic pattern of \mathbf{X}_H of length n .

Proof. Since (\mathcal{A}, M) is definite, we have

$$\underline{P}_n(\mathbf{X}_H) = \sum_{\substack{u \neq \varepsilon, v, p, q \\ uv \in H_{pq}}} [v(\sum_{k \geq 1} H^k)_{qp}u]_n.$$

Thus

$$\begin{aligned} \pi(\underline{P}_n(\mathbf{X}_H)) &= \sum_{\substack{p, q, 1 \leq j \leq |uv| \\ uv \in H_{pq}}} [uv]_j[\pi H^k]_{qp}]_{n-j}, \\ &= \text{tr}[\pi H_\sigma(1 - \pi H)^{-1}]_n, \\ &= \text{tr} \sum_{1 \leq j \leq n} j[\pi H]_j[(1 - \pi H)^{-1}]_{n-j}. \end{aligned}$$

Note that the pseudo inverse $(1 - \pi H)$ of πH exists since πH belongs to $(Q \times Q)^{\mathbb{Z}\langle\langle A \rangle\rangle}$. \square

Proposition 4. *Let (\mathcal{A}, M) be a left-reduced definite Dyck automaton and H be one of the matrices C, C_c, M_c in $(Q \times Q)^{\mathbb{Z}\langle\langle A \rangle\rangle}$ defined above. We have*

$$\zeta(\mathbf{X}_C)(z) = \frac{1}{\det(I - H(z))},$$

where $H(z) = \theta\pi H$.

Proof. From Proposition 3, we get

$$\begin{aligned} &\sum_{n \geq 1} \frac{\theta\pi \underline{P}_n(\mathbf{X}_H)}{n} \\ &= \sum_{n \geq 1} \frac{1}{n} \text{tr} \sum_{j=1}^n j[\theta\pi H]_j[(I - \theta\pi H)^{-1}]_{n-j}, \\ &= \sum_{n \geq 1} \frac{1}{n} \text{tr} \sum_{j=0}^{n-1} (j+1)[\theta\pi H]_{j+1}[(I - \theta\pi H)^{-1}]_{n-j-1}, \\ &= \sum_{n \geq 1} \frac{1}{n} \text{tr} \sum_{j=0}^{n-1} [d\theta\pi H]_j[(I - \theta\pi H)^{-1}]_{n-j-1}, \\ &= \sum_{n \geq 1} \frac{1}{n} \text{tr}[(d\theta\pi H)(I - \theta\pi H^{-1})]_{n-1}, \end{aligned}$$

$$\begin{aligned}
 &= \sum_{n \geq 1} \frac{1}{n} \operatorname{tr}[(d\theta\pi H)(I - \theta\pi H^{-1})]_{n-1}, \\
 &= \sum_{n \geq 1} \operatorname{tr} \frac{1}{n} [(d\theta\pi H)(I - \theta\pi H^{-1})]_{n-1}, \\
 &= \sum_{n \geq 1} \operatorname{tr}[-(\log(I - \theta\pi H))_n], \\
 &= \operatorname{tr} -\log(I - \theta\pi H).
 \end{aligned}$$

Thus, using Jacobi's formula, we obtain

$$\begin{aligned}
 \zeta(X_C)(z) &= \exp \operatorname{tr} -\log(I - \theta\pi H), \\
 &= \det \exp -\log(I - \theta\pi H), \\
 &= \frac{1}{\det(I - \theta\pi H)},
 \end{aligned}$$

where d denotes the derivative with respect to the variable z . □

We have a similar formula with a right reduced definite Dyck automaton and H one of the matrices C' , C_c , M_r .

3.4. \mathbb{N} -algebraicity of the zeta function of finite-type-Dyck shifts.

In this section, we prove that the zeta function of a finite-type Dyck shift is \mathbb{N} -algebraic, *i.e.* that it is the generating series of an unambiguous context-free language. Actually, we prove a more precise result. The zeta function is the generating series of a visibly pushdown language.

More precisely, a series $S(z)$ is \mathbb{N} -algebraic if and only if it has its coefficients in \mathbb{N} and if $S(z) - S(0)$ is the first component of the solution of a proper positive system, *i.e.* a system of equations of the form $S_i = P_i(z, S_1, \dots, S_k)$, for some polynomials $P_i(z, x_1, \dots, x_k)$ having coefficients in \mathbb{Z} . The system is said to be proper if P_i has no constant term ($P_i(0, \dots, 0) = 0$) and does not contain any linear term x_i . It is positive if the coefficients of the P_i are nonnegative.

A series $S(z)$ is \mathbb{N} -algebraic if and only if $S(0) \in \mathbb{N}$ and there exists an unambiguous context-free language having generating function $S(z) - S(0)$ (Chomsky-Schützenberger theorem [16]).

There is no known criterion for a \mathbb{Z} -algebraic series with coefficients in \mathbb{N} to be \mathbb{N} -algebraic but recent insights from Banderier and Drmota [5, 4] provide some necessary conditions. Banderier and Drmota solved a conjecture on the asymptotic behavior of the coefficients, known to be of the form $\kappa \lambda^n n^\alpha$, which says that the appearing critical exponents α belong to a subset of dyadic numbers. Their result extends the Drmota-Lalley-Woods theorem which assures that $\alpha = -3/2$ as soon as some dependency graph associated to the algebraic system defining the series is strongly connected.

Rational and algebraic formal power series are well-behaved objects with many interesting properties.

Theorem 1. *The zeta function of a finite-type-Dyck shift is \mathbb{N} -algebraic.*

Proof. From Section 3.3 we get,

$$\zeta_X(z) = \det(I - \theta\pi C_c)^{-1} \det(I - \theta\pi C_r)^{-1} \\ \det(I - \theta\pi M_c)^{-1} \det(I - \theta\pi M_r)^{-1} \det(I - \theta\pi C),$$

where the matrices are defined as in Section 3.3. Thus

$$\zeta_X(z) = \det(I - \theta\pi C) \\ \det(I - \theta\pi C M_c^*)^{-1} \det(I - \theta\pi M_c)^{-1} \\ \det(I - \theta\pi M_r)^{-1} \det(I - \theta\pi M_r^* C')^{-1}.$$

Since

$$(I - C M_c^*)(I - M_c) = (I - C \frac{1}{I - M_c})(I - M_c) \\ = (I - C - M_c),$$

and similarly $(I - M_r)(I - M_r^* C') = (I - M_r - C')$, we get that

$$\zeta_X(z) = \det(I - \theta\pi C) \det(\theta\pi(I - C - M_r)(I - C' - M_r))^{-1}, \\ = \det(\theta\pi(I - C^* M_c)(I - M_r - C'))^{-1}, \\ = \det(I - \theta\pi C^* M_c)^{-1} \det(I - \theta\pi(M_r + C'))^{-1}.$$

Now we use the classical formula for computing $\det(I - N)$ for an $R \times R$ -matrix N with noncommutative entries (see for instance [19, Section 7.4]). The matrix defines a labelled graph \mathcal{G} with R as set of vertices and (p, N_{pq}, q) as edges. Set $R = \{1, 2, \dots, |R|\}$ and denote by $Y_{N,i}$ the set of labels of first-return paths from i to i in \mathcal{G} after removing the lines and columns $1, 2, \dots, i-1$ of the matrix N . We have

$$\det(I - N) = \prod_{i=1}^{|R|} (1 - Y_{N,i}).$$

It follows that, if C (resp. C') is a $Q \times Q$ -matrix (resp. a $Q' \times Q'$ -matrix),

$$\zeta_X(z) = \prod_{i=1}^{|Q|} Y_{C^* M_c, i}^* \prod_{i=1}^{|Q'|} Y_{M_r + C', i}^*,$$

which ends the proof. \square

3.5. Zeta function of sofic-Dyck shifts. In the case of sofic-Dyck shifts, we recall the computation of the zeta function performed in [9] for sofic shifts having a deterministic Dyck automaton. It extends now to all sofic-Dyck shifts. This proves that all sofic-Dyck shifts have a \mathbb{Z} -algebraic zeta function.

We first need some machinery similar to the one used to count periodic points of sofic shifts (see for instance [33]).

Let $(\mathcal{A} = (Q, E, A), M)$ be a Dyck automaton. Let $(\mathcal{A}_{\otimes \ell}$ be the labelled graph whose set of states is the set $Q_{\otimes \ell}$ of all subsets of Q having ℓ elements. We fix an ordering on the states in each element of $Q_{\otimes \ell}$. Let $P = (p_1, \dots, p_\ell)$, $P' = (p'_1, \dots, p'_\ell)$ be two states of $Q_{\otimes \ell}$ with $p_1 < \dots < p_\ell$ and $p'_1 < \dots < p'_\ell$ according to this ordering. There is an edge labelled by a from P to P' in $\mathcal{A}_{\otimes \ell}$ if and only if there are edges labelled by a from p_i to q_i for $1 \leq i \leq \ell$ and (q_1, \dots, q_ℓ) is an even permutation of P' . If the permutation is odd we assign the label $-a$. Otherwise, there is no edge with label $+a$ or a from P to P' . The labelled graph $\mathcal{A}_{\otimes \ell}$ is a Dyck automaton on the alphabet $A' = (A'_c, A'_r, A'_i)$ with $A'_c = A_c \cup \{-a \mid a \in A_c\}$, $A'_r = A_r \cup \{-a \mid a \in A_r\}$, and $A'_i = A_i \cup \{-a \mid a \in A_i\}$.

We define $M_{\otimes \ell}$ as the set of pairs of edges $((p_1, \dots, p_\ell), a, (p'_1, \dots, p'_\ell))$, $(r_1, \dots, r_\ell), +/ - b, (r'_1, \dots, r'_\ell)$ of $\mathcal{A}_{\otimes \ell}$ such that each edge (p_i, a, p'_i) is matched with (r_i, b, r'_i) for $1 \leq i \leq n$. We say that a path of $\mathcal{A}_{\otimes \ell}$ is *admissible* if it is admissible when the signs of the labels are omitted, the sign of the label of a path being the product of the signs of the labels of the edges of the path.

Let (\mathcal{A}, M) (resp. (\mathcal{A}', M')) be a left-reduced (resp. a right-reduced) Dyck automaton X . In the sequel H denotes one of the matrices C, C_c, M_c in $(Q \times Q)^{\mathbb{Z}\langle\langle A \rangle\rangle}$ defined in Section 3.3. We denote by $H_{\otimes \ell}$ the matrices defined from $(\mathcal{A}_{\otimes \ell}, M_{\otimes \ell})$ similarly. The matrices C', C_r, M_r $(Q' \times Q')^{\mathbb{Z}\langle\langle A \rangle\rangle}$ are defined similarly from a left-reduced Dyck automaton accepting X . We denote by $H'_{\otimes \ell}$ the matrices defined from $(\mathcal{A}'_{\otimes \ell}, M'_{\otimes \ell})$ similarly.

The following result was established in [9] for deterministic presentations. It holds for reduced presentations (\mathcal{A}, M) and (\mathcal{A}', M') .

$$\zeta_{X_H}(z) = \prod_{\ell=1}^{|Q|} \det(I - \theta \pi H_{\otimes \ell}(z))^{(-1)^\ell},$$

where H is either C, C_c or M_c . Similar formula holds for H' is either C', C_r or M_r .

Proposition 5. *The zeta function $\zeta_X(z)$ of a sofic-Dyck shift is equal to*

$$\begin{aligned} & \prod_{\ell=1}^{|Q|} \det(I - \theta \pi C_{c, \otimes \ell}(z))^{(-1)^\ell} \det(I - \theta \pi M_{c, \otimes \ell}(z))^{(-1)^\ell} \\ & \prod_{\ell=1}^{|Q'|} \det(I - \theta \pi C_{r, \otimes \ell}(z))^{(-1)^\ell} \det(I - \theta \pi M_{r, \otimes \ell}(z))^{(-1)^\ell} \\ & \prod_{\ell=1}^{|Q|} \det(I - \theta \pi C_{\otimes \ell}(z))^{(-1)^\ell + 1}, \end{aligned}$$

where $H_{\otimes \ell}(z) = \theta \pi H_{\otimes \ell}$, for $H_{\otimes \ell} = C_{\otimes \ell}, C_{c, \otimes \ell}, C_{r, \otimes \ell}, M_{c, \otimes \ell}, M_{r, \otimes \ell}$, defined above.

Example 3. Let X be the sofic-Dyck shift of Example 2. The Dyck automaton $\mathcal{A}_{\otimes 1}$ is the same as \mathcal{A} . The Dyck automaton $\mathcal{A}_{\otimes 2}$ is pictured on the right part of Figure 4. Let us compute the zeta function of $X_{\mathcal{C}}$ for this

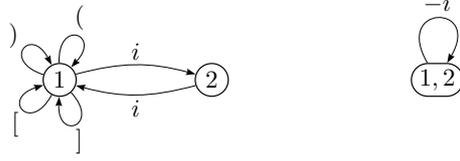


FIGURE 4. The Dyck automaton (\mathcal{A}, M) over $A = (\{(\cdot, [\cdot], \cdot), \cdot\}, \{i\})$ (on the left) and the Dyck automaton $\mathcal{A}_{\otimes 2}$ on the right.

automaton. We have

$$C = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}, \quad C_{\otimes 2} = [C_{(1,2),(1,2)}].$$

We have

$$\begin{aligned} C_{11} &= (D_{11}) + [D_{11}], \\ C_{22} &= 0, \\ C_{12} &= i, \\ C_{21} &= i, \end{aligned}$$

with $D_{11} = (D_{11}) D_{11} + [D_{11}] D_{11} + iiD_{11} + \varepsilon$. Hence

$$2z^2 D_{11}^2(z) - (1 - z^2)D_{11}(z) + 1 = 0$$

Since $[z^0]D_{11}(z) = 1$, we get

$$D_{11}(z) = \frac{1 - z^2 - \sqrt{1 - 10z^2 + z^4}}{4z^2}.$$

Hence

$$C_{11}(z) = 2z^2 D_{11}(z) = \frac{1 - z^2 - \sqrt{1 - 10z^2 + z^4}}{2}.$$

We have $C_{22}(z) = 0$, $C_{12}(z) = C_{21}(z) = z$. We also have $C_{(1,2),(1,2)} = -i$ and thus $C_{(1,2),(1,2)}(z) = -z$. Thus

$$\begin{aligned} \zeta_{X_{\mathcal{C}}}(z) &= \prod_{\ell=1}^2 \det(I - \theta \pi C_{\otimes \ell}(z))^{(-1)^\ell} \\ &= (1 + z) \left| \begin{array}{cc} 1 - \frac{1 - z^2 - \sqrt{1 - 10z^2 + z^4}}{2} & -z \\ -z & 1 \end{array} \right|^{-1}, \\ &= \frac{1 + z}{1 - z^2 - \frac{1 - z^2 - \sqrt{1 - 10z^2 + z^4}}{2}}. \end{aligned}$$

For $H = M_c, M_r$, we have

$$\prod_{\ell=1}^2 \det(I - \theta\pi H_{\otimes\ell}(z))^{(-1)^\ell} = \frac{1}{1-2z}.$$

We also have

$$\begin{aligned} C_c &= CM_c^* = \begin{bmatrix} C_{11} & i \\ i & 0 \end{bmatrix} \begin{bmatrix} \{(\cdot, \cdot)\}^* & 0 \\ 0 & \varepsilon \end{bmatrix} = \begin{bmatrix} C_{11}\{(\cdot, \cdot)\}^* & i \\ i\{(\cdot, \cdot)\}^* & 0 \end{bmatrix}, \\ C_r &= M_r^*C = \begin{bmatrix} \{(\cdot, \cdot)\}^* & 0 \\ 0 & \varepsilon \end{bmatrix} \begin{bmatrix} C_{11} & i \\ i & 0 \end{bmatrix} = \begin{bmatrix} \{(\cdot, \cdot)\}^*C_{11} & \{(\cdot, \cdot)\}^*i \\ i & 0 \end{bmatrix}. \end{aligned}$$

$$\begin{aligned} \prod_{\ell=1}^2 \det(I - \theta\pi C_{c,\otimes\ell}(z))^{(-1)^\ell} &= (1+z) \begin{vmatrix} 1 - \frac{C_{11}(z)}{(1-2z)} & -z \\ -\frac{z}{1-2z} & 1 \end{vmatrix}^{-1} \\ &= \frac{(1+z)(1-2z)}{1-2z-z^2-C_{11}(z)}. \end{aligned}$$

The same equality holds for C_r . We finally get

$$\begin{aligned} \zeta_X(z) &= \frac{(1+z)(1-z^2-C_{11}(z))}{(1-2z-z^2-C_{11}(z))^2}, \\ &= \frac{(1+z)}{(1-2z(z^2+C_{11}(z))^*(1-2z-z^2-C_{11}(z)))}, \\ &= (1+z)(2z(z^2+C_{11}(z))^*)^*(2z+z^2+C_{11}(z))^*. \end{aligned}$$

Since $C_{11}(z)$ is the generating series of a visibly pushdown language, $\zeta_X(z)$ is an \mathbb{N} -algebraic series. The asymptotic behavior of the coefficients z^n in $\zeta_X(z)$ is $\kappa\lambda^n n^{-3/2}$, where

$$\lambda = \frac{2}{\sqrt{13}-3}$$

This is a typical behavior for an \mathbb{N} -algebraic series (see [5, 4] and [17]). The topological entropy of the sofie-Dyck shift is $\log \lambda \sim \log 3.3027$.

We conjecture that the zeta function of a sofie-Dyck shift is always \mathbb{N} -algebraic.

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